

# MRI Physics:

# Magnetic Field Gradients

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# Pulse Sequences

- Contrast (Spin Preparation)

What kind of contrast does the image have?  
What is the TR, TE, Flip Angle, etc.?  
Gradient echo/spin echo/etc.

- Localization (Image Acquisition)

How is the image acquired?  
How is “k-space” sampled?  
Spatial Resolution? Field-of-View?

# Goals of Image Acquisition

- Acquire 2D (or 3D) Fourier data
- Acquire samples finely enough to prevent aliasing (FOV)
- Acquire enough samples for the desired spatial resolution ( $\Delta x$ )
- Acquire images with the right contrast
- Do it fast as possible
- Do it without distortions and other artifacts

# Magnetic Fields in MRI

$B_0$  – The main magnetic field

Always on (0.5-7 T)

Magnetizes the object to be imaged

After excitation, the magnetization precesses around  $B_0$  at  $\omega_0 = \gamma B_0$

$B_1$  – The rotating RF magnetic field

Tips magnetization into transverse plane

Used for “excitation”

On for brief periods, then off

# Magnetic Fields in MRI

The last magnetic field to be used in MRI are the gradient fields

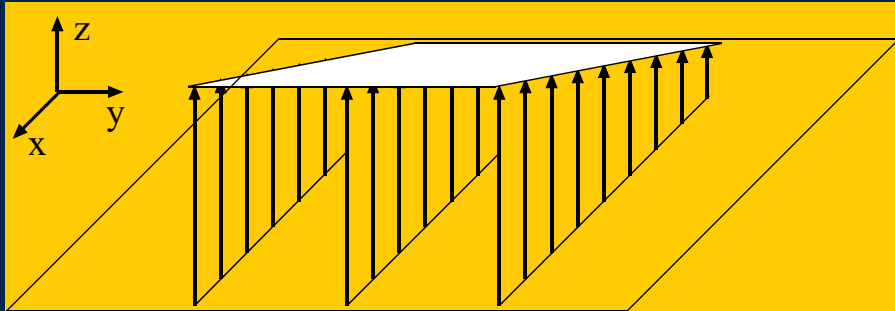
3 of them:  $G_x$ ,  $G_y$ ,  $G_z$

Used primarily for spatial localization

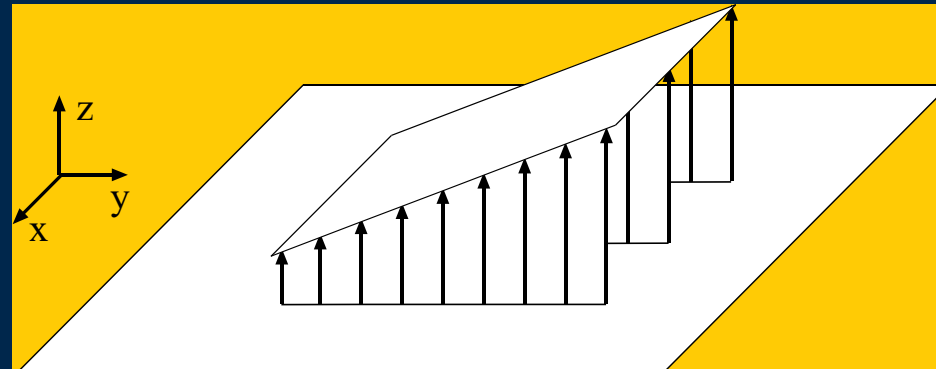
Make the magnetic field different in different parts of the body,  
e.g. for the x-gradient:

$$B(x) = B_0 + G_x \cdot x$$

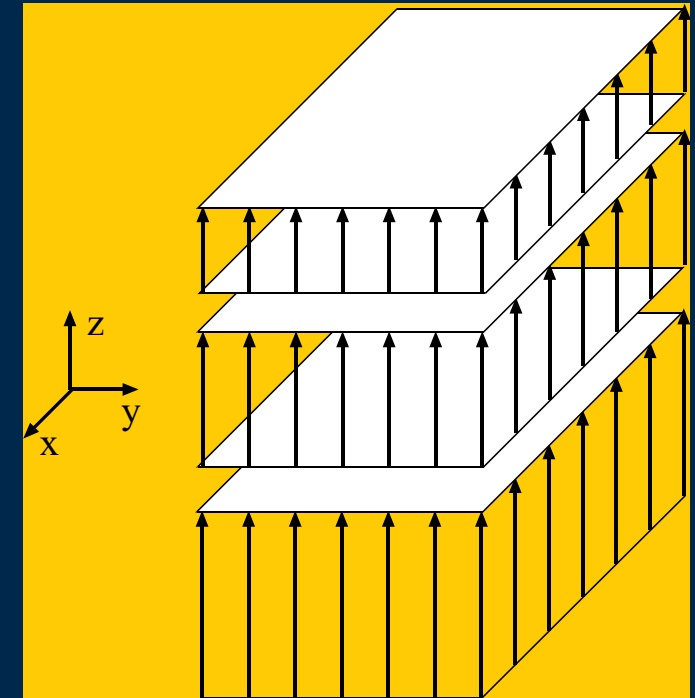
# Magnetic Field Gradients



x-gradient ( $G_x$ )

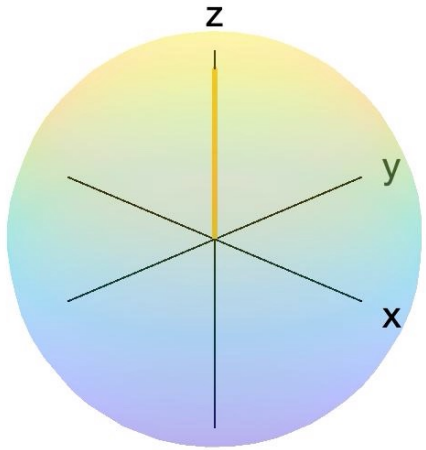


y-gradient ( $G_y$ )



z-gradient ( $G_z$ )

# Precession



$$\omega = \gamma \cdot B_0$$

Larmor Frequency  
Angular Frequency

Gyromagnetic Ratio

Main Magnetic Field

$B_0=1.5\text{T} \rightarrow \omega = 64 \text{ MHz} \rightarrow 64 \text{ million rounds/sec}$

$B_0=3.0\text{T} \rightarrow \omega = 128 \text{ MHz} \rightarrow 128 \text{ million rounds/sec}$

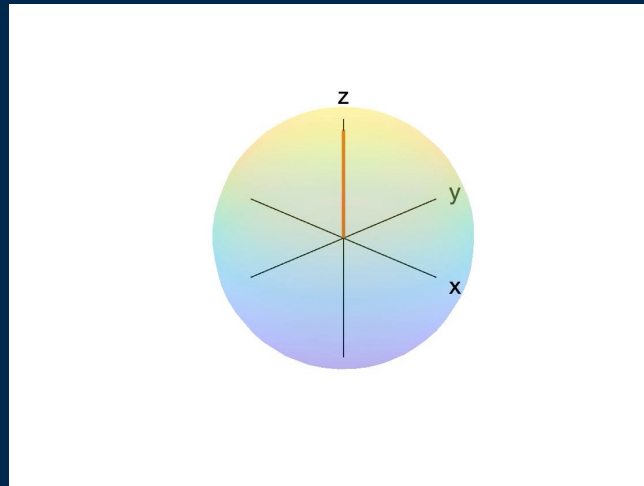
Stronger Magnetic Field = Faster precession

# Precession Frequency can be altered with magnetic field gradients

$$B(x) = B_0 + G_x x$$

$$\omega = \gamma \cdot B$$

$$\omega(x) = \gamma B(x) = \gamma(B_0 + G_x x)$$





# Precession Frequency can be altered with magnetic field gradients



$$B(x) = B_0 + G_x \cdot x$$

$$\omega(x) = \gamma B(x) = \gamma(B_0 + G_x \cdot x)$$

$x=0$

$x=X$

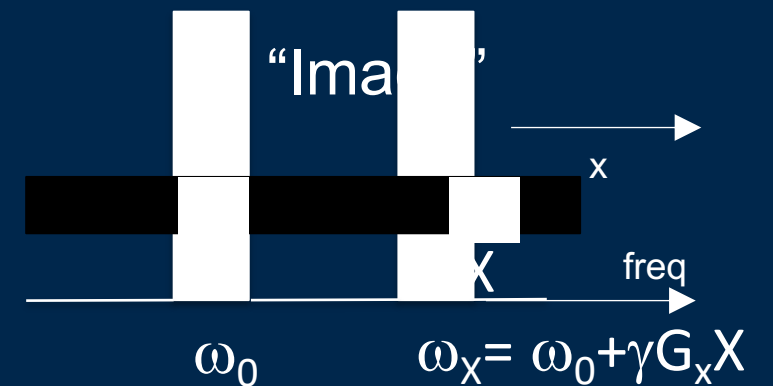
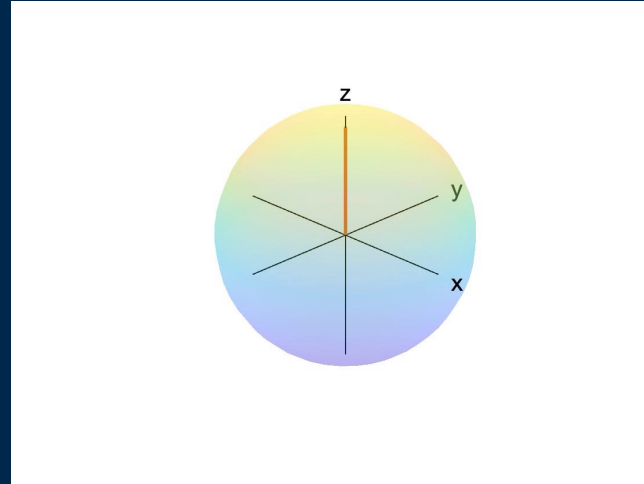


$B=B_0$

$B_x=B_0+G_x X$

$\omega = \omega_0$

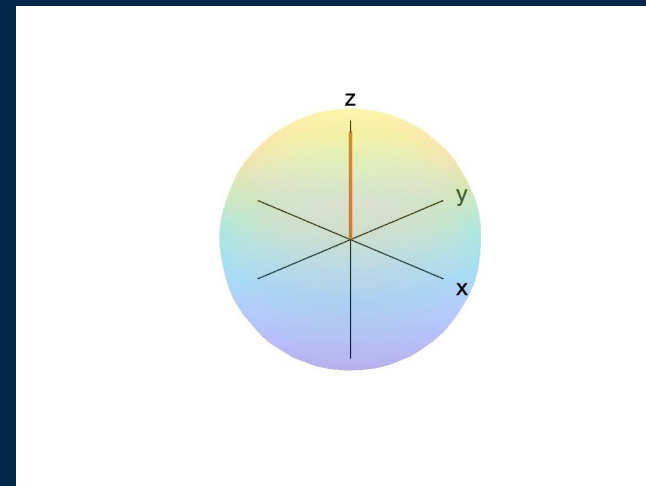
$\omega_x = \omega_0 + \gamma G_x X$



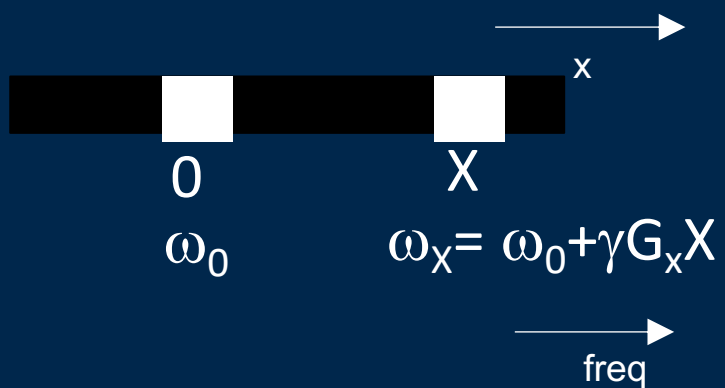
# The Challenge



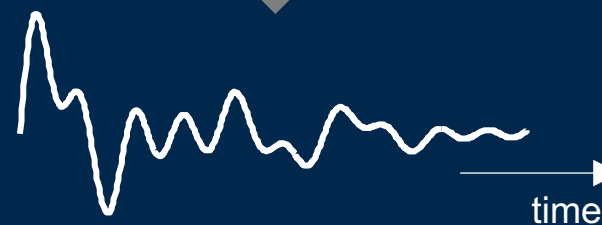
Pulse Sequence  
(with Gradients)



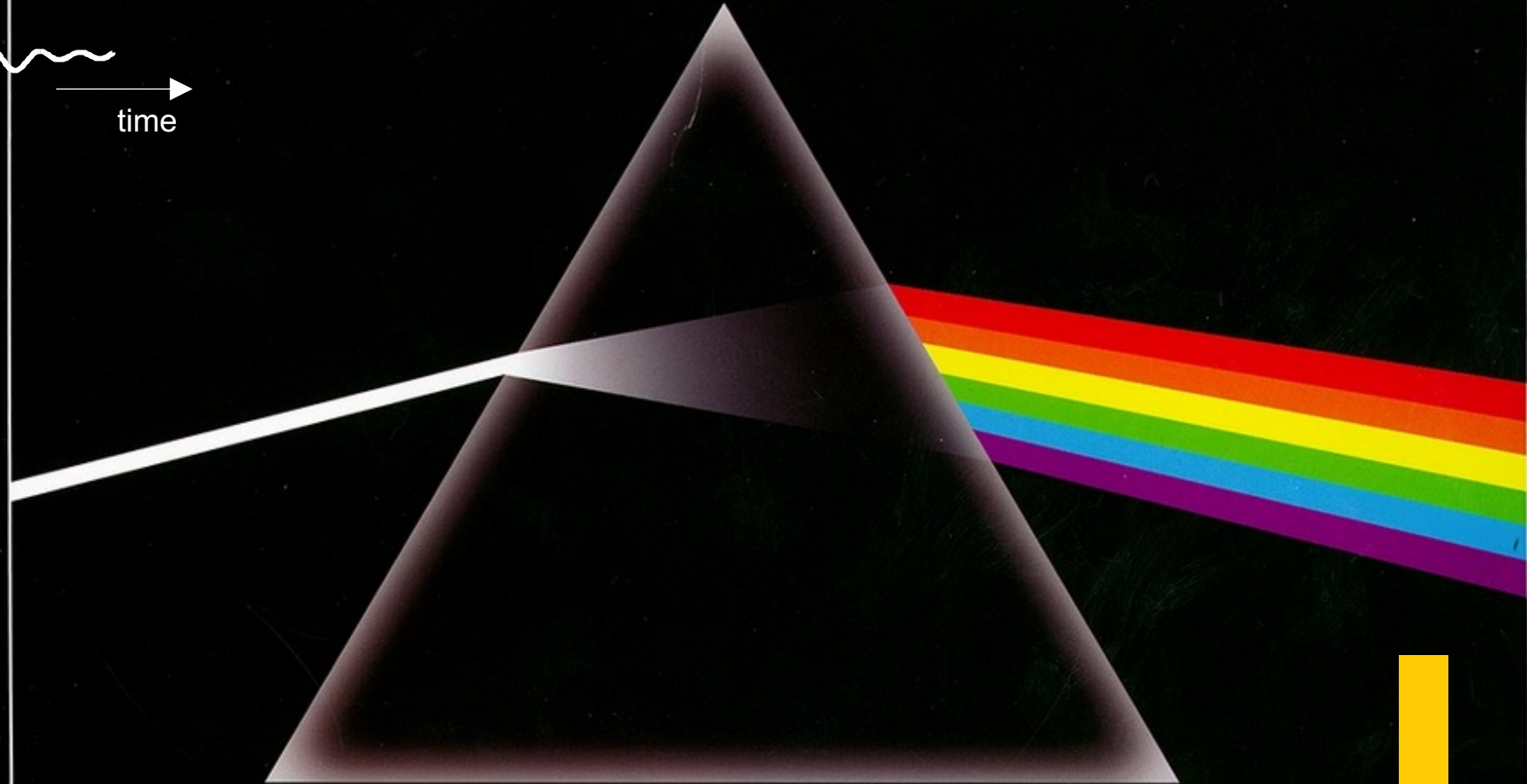
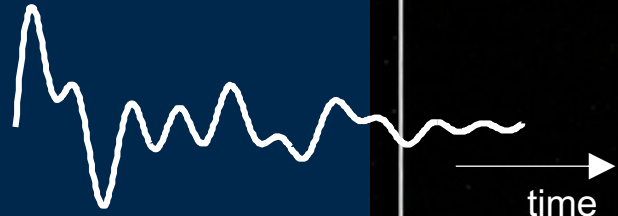
Data  
Collection



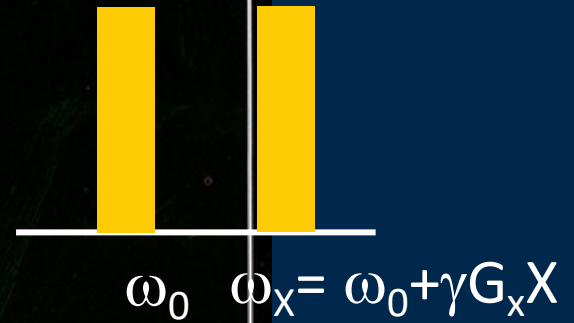
????



# PINK FLOYD



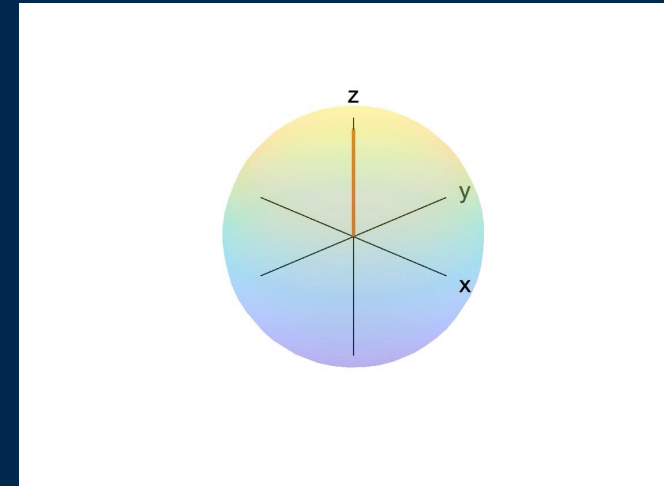
THE DARK SIDE OF THE MOON



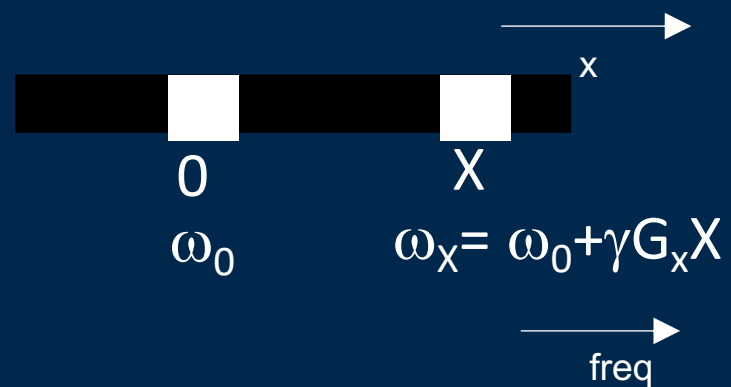
# The Challenge



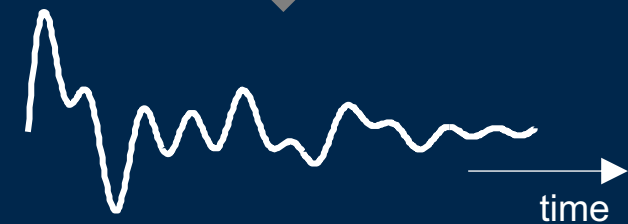
Pulse Sequence  
(with Gradients)



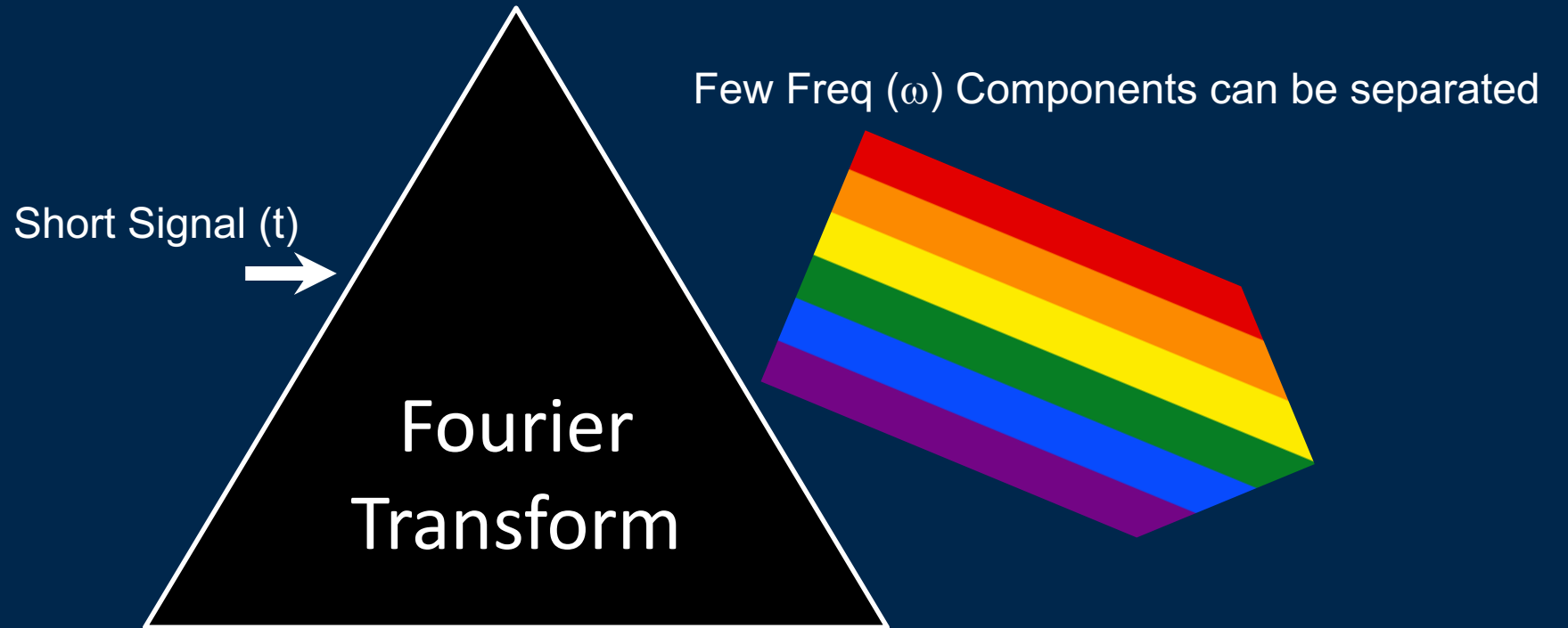
Data  
Collection



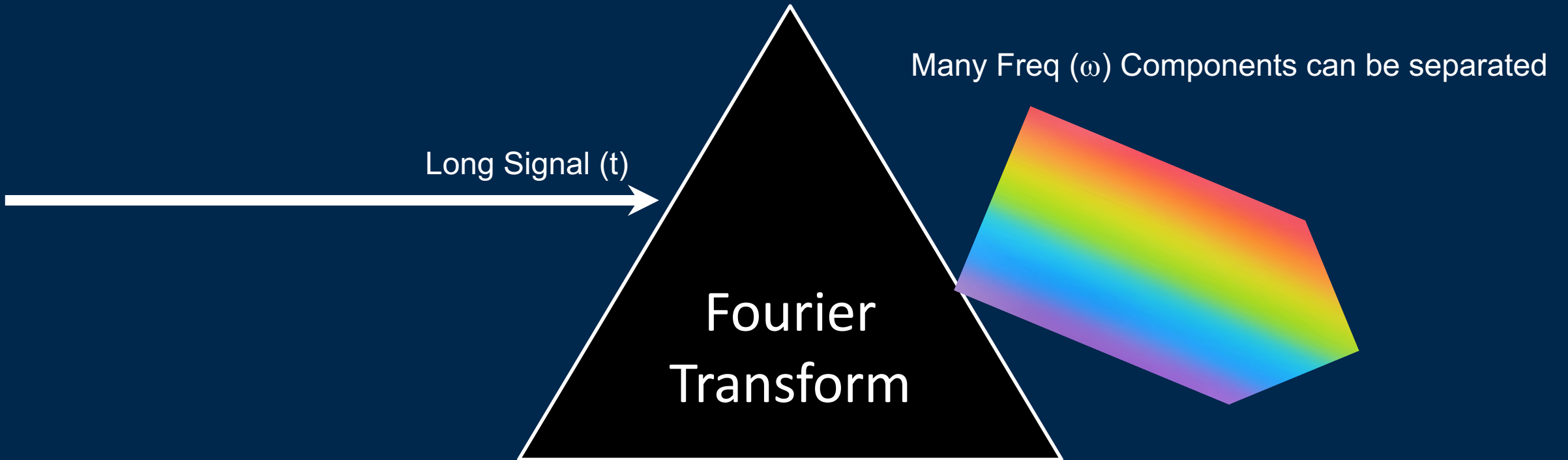
Fourier  
Transform!!



# Signal Length $\rightarrow$ Freq Resolution



# Signal Length $\rightarrow$ Freq Resolution



# MRI Physics:

## Frequency and Phase Encoding

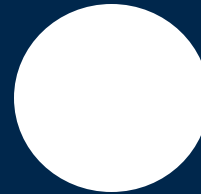
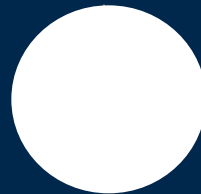
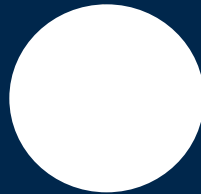
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# Spatial Localization



MR signals

$$\text{wavy line} + \text{wavy line} + \text{wavy line} = \text{combined wavy line}$$



$B_0$



$$\omega = \gamma B_0$$



# Spatial Localization

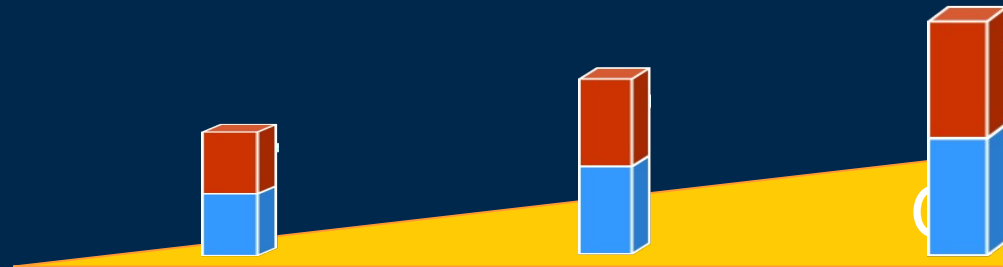
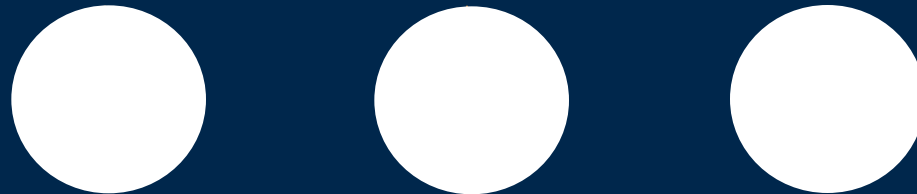


MR signals



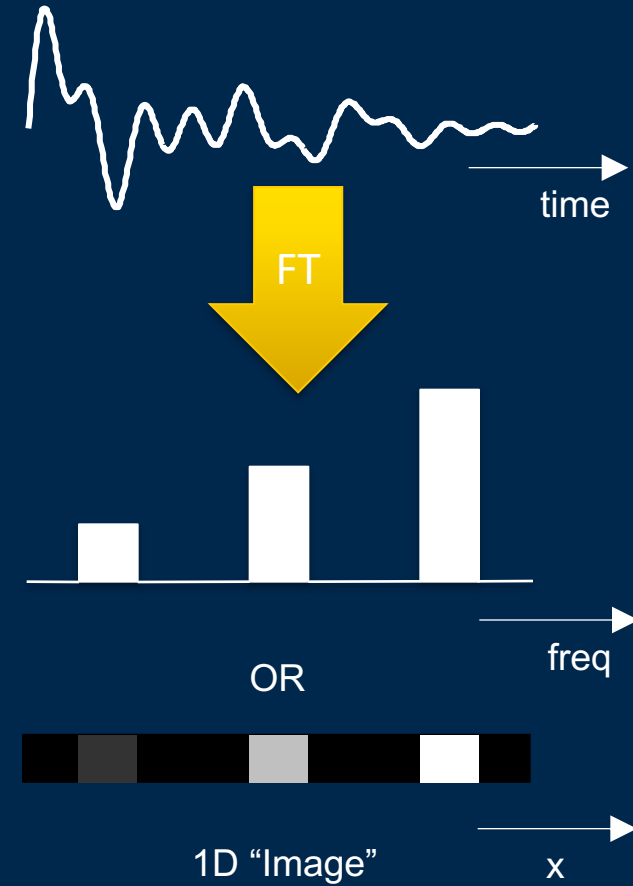
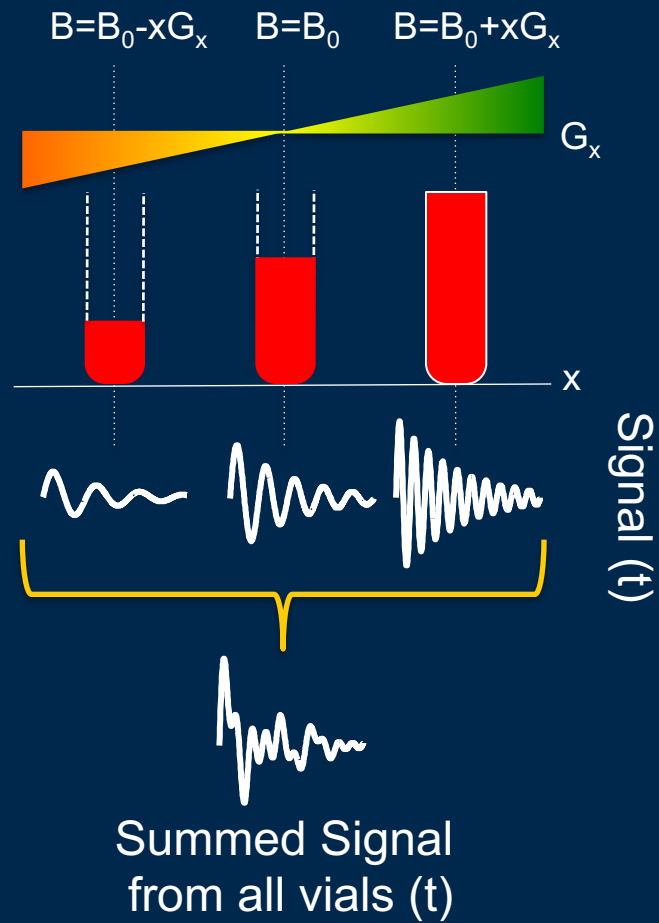
Fourier transform

Raw data

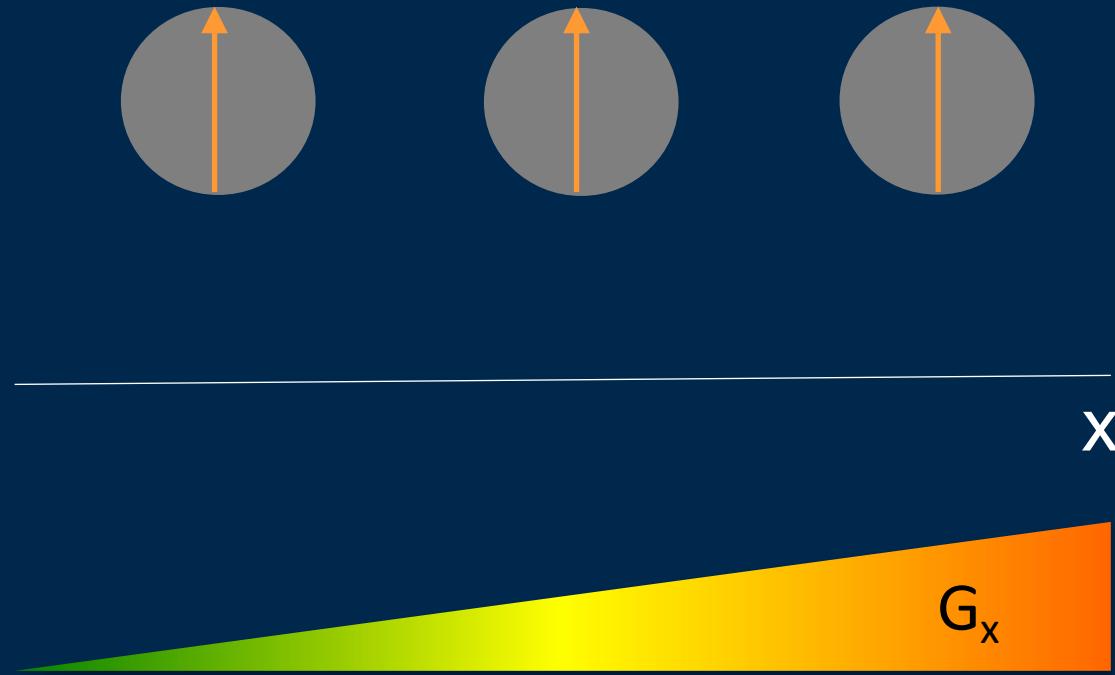


$$\omega(x) = \gamma B(x) = \gamma(B_0 + G_x \cdot x)$$

# Frequency Encoding



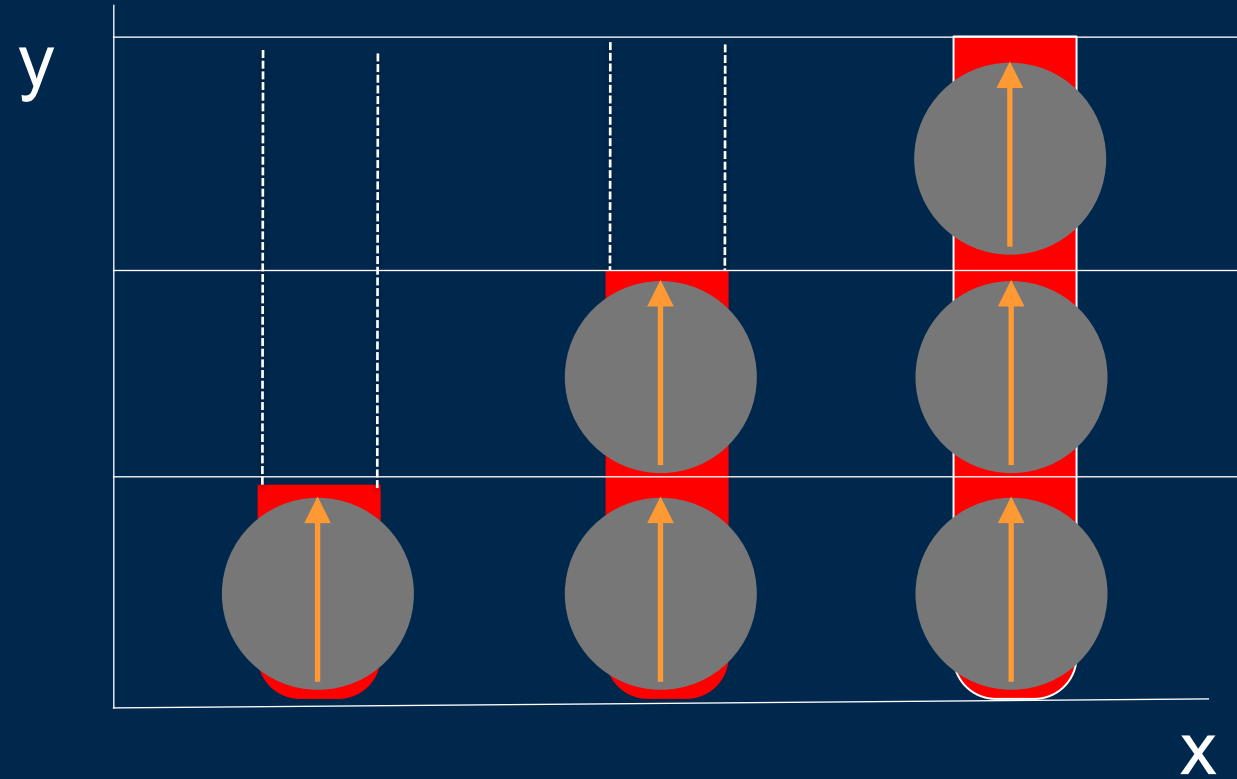
# Gradients alter frequency and phase of spins



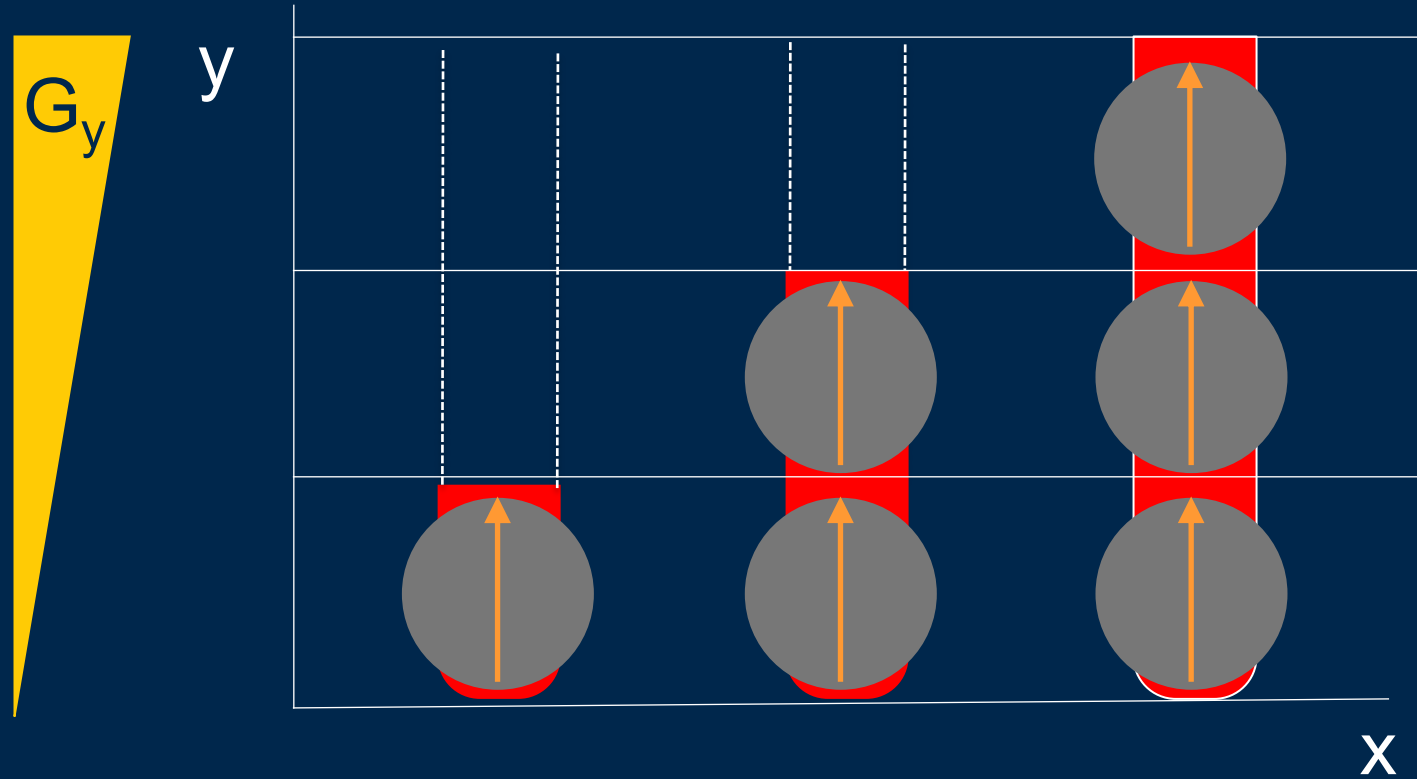
Frequency → how fast spins precess

Phase → relative orientation with respect to one another

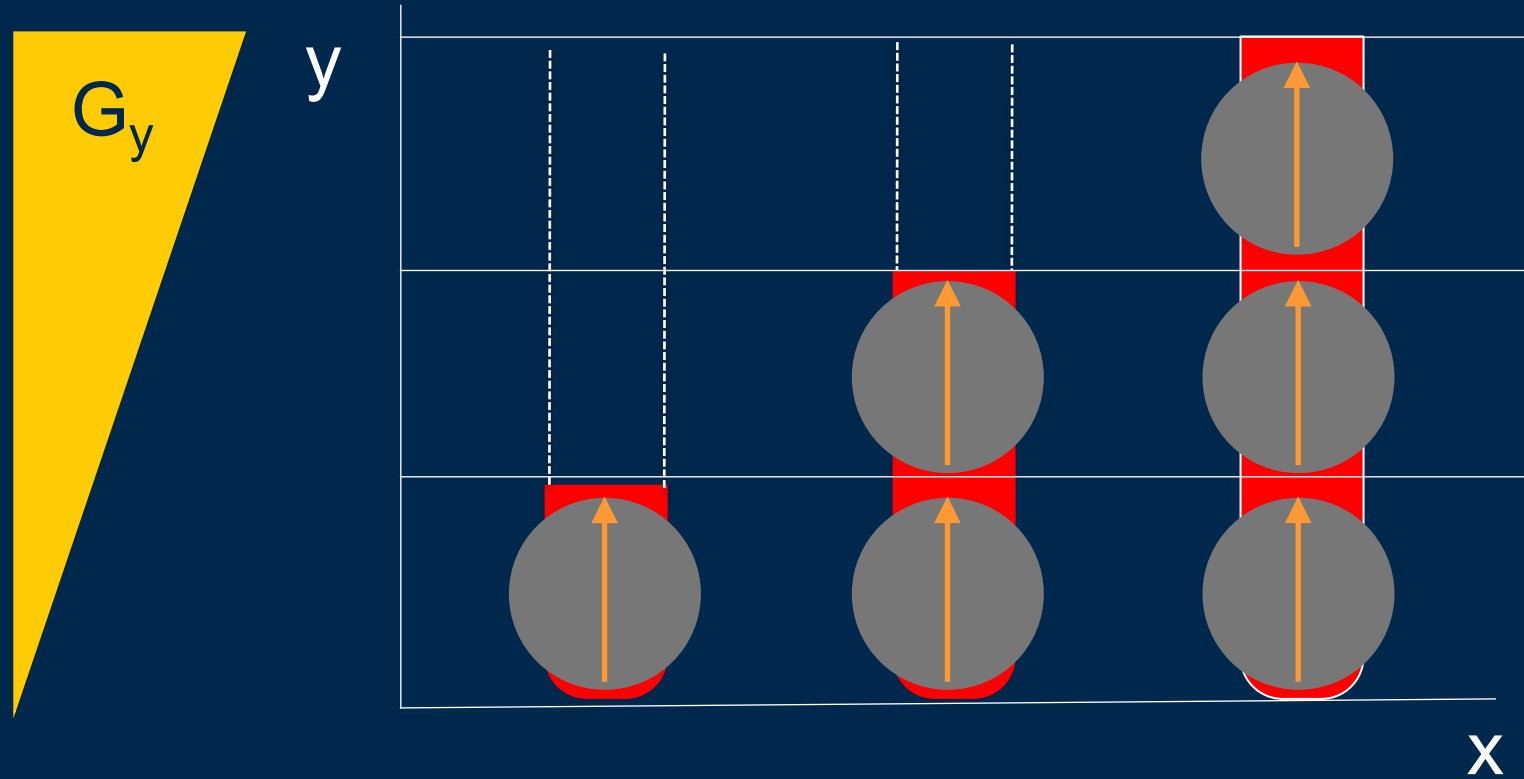
# Phase Encoding



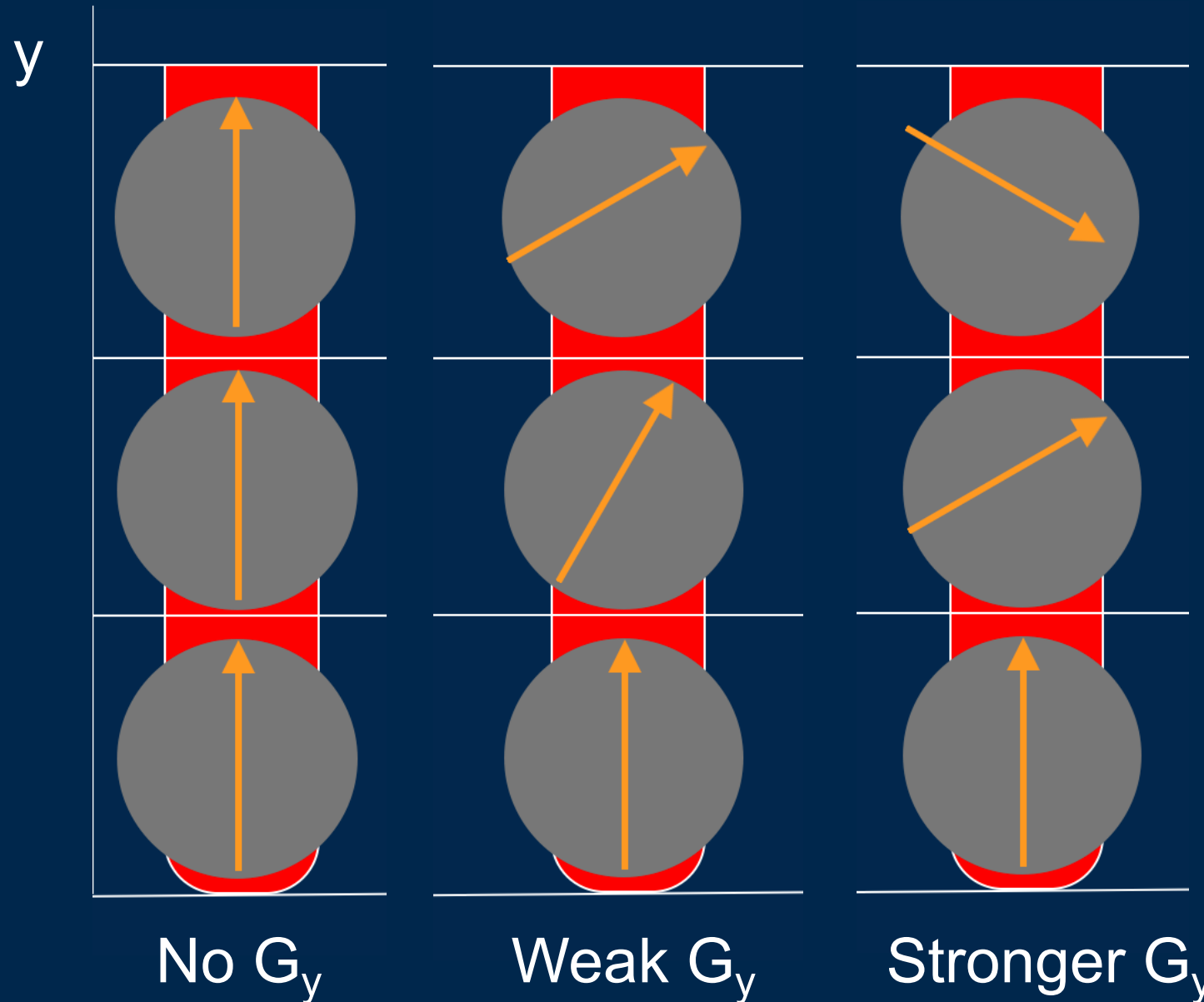
# Phase Encoding



# Phase Encoding



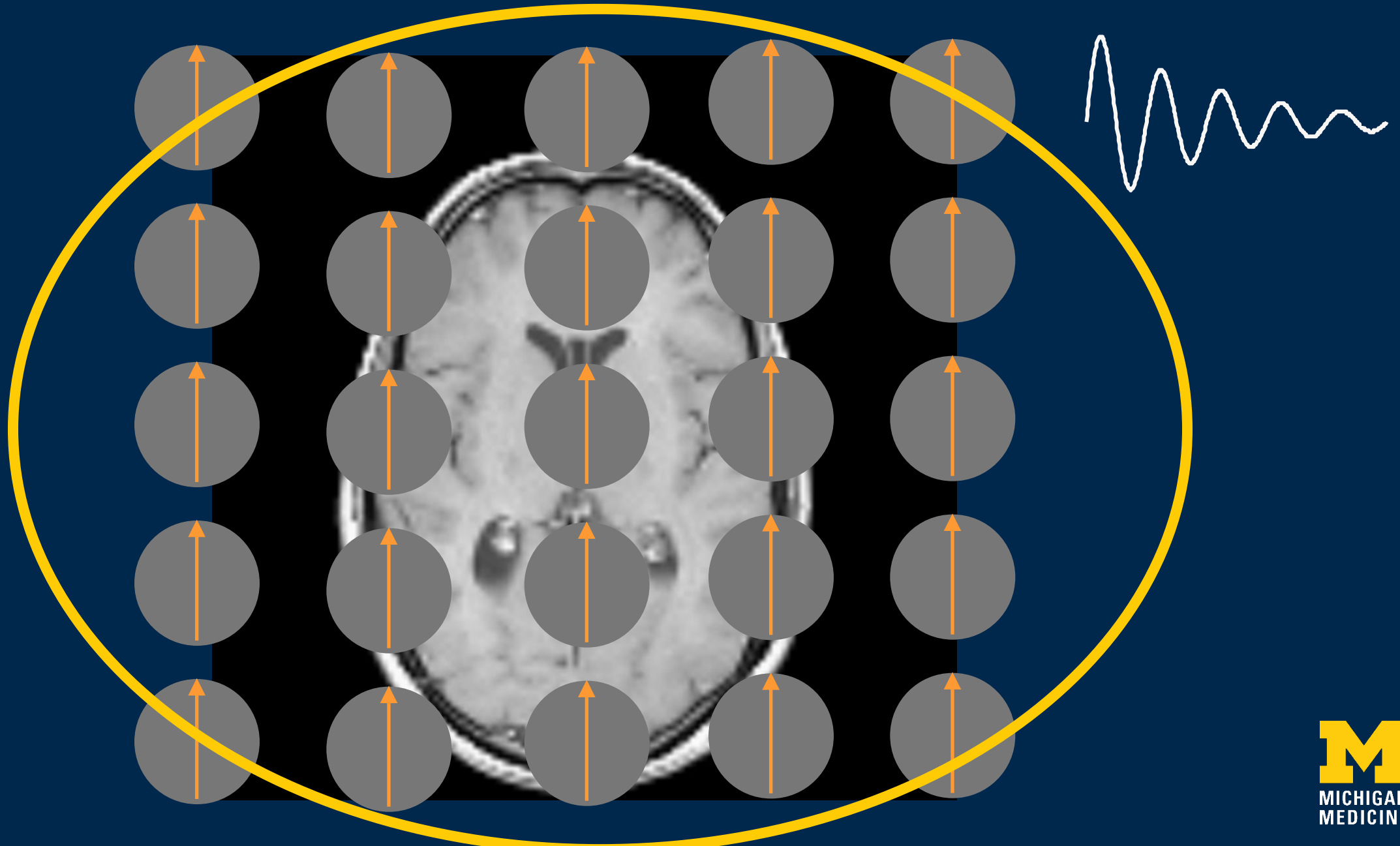
# Phase Encoding → Just like Freq Encoding



Phase Encoding works just like Frequency Encoding

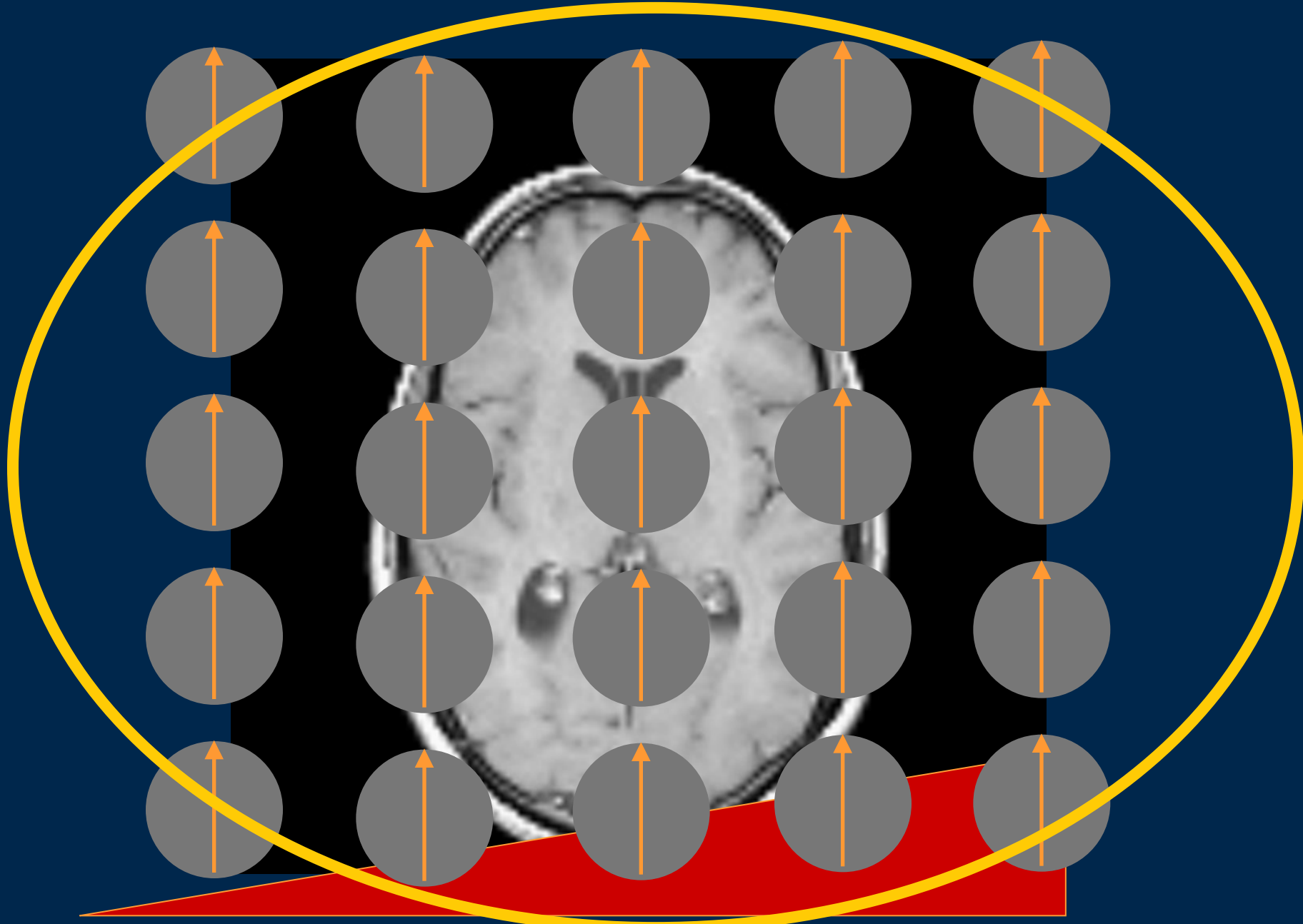
→ Imparts spatial dependent frequency which can be extracted using Fourier Transform

# Spins in Constant Magnetic Field

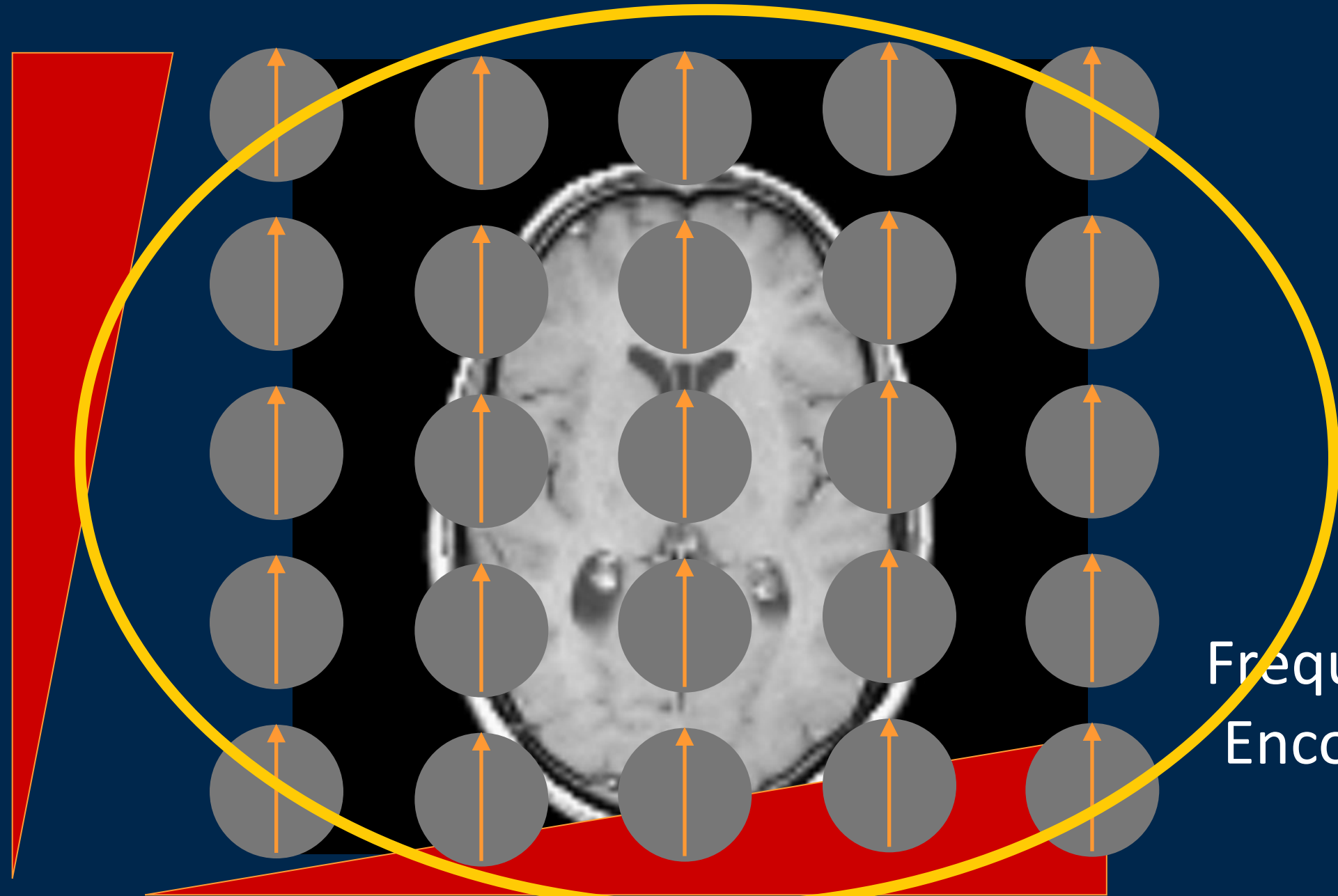




# Frequency Encoding



# Phase Encoding



Frequency  
Encoding

# Signal Equation and Fourier MRI

$$s(x, y, t) = \rho(x, y) \cdot e^{-i\omega t} = \rho(x, y) \cdot e^{-i\gamma B_0 t}$$

$$s(x, y, t, \tau) = \rho(x, y) \cdot e^{-i\gamma(B_0 + G_x)x \cdot t} \cdot e^{-i\gamma(B_0 + G_y)y \cdot \tau}$$

$$S(t, \tau) = \iint s(x, y, t, \tau) dx dy$$

$$= \iint \rho(x, y) \cdot e^{-i\gamma(B_0 + G_x)x \cdot t} \cdot e^{-i\gamma(B_0 + G_y)y \cdot \tau} dx dy$$

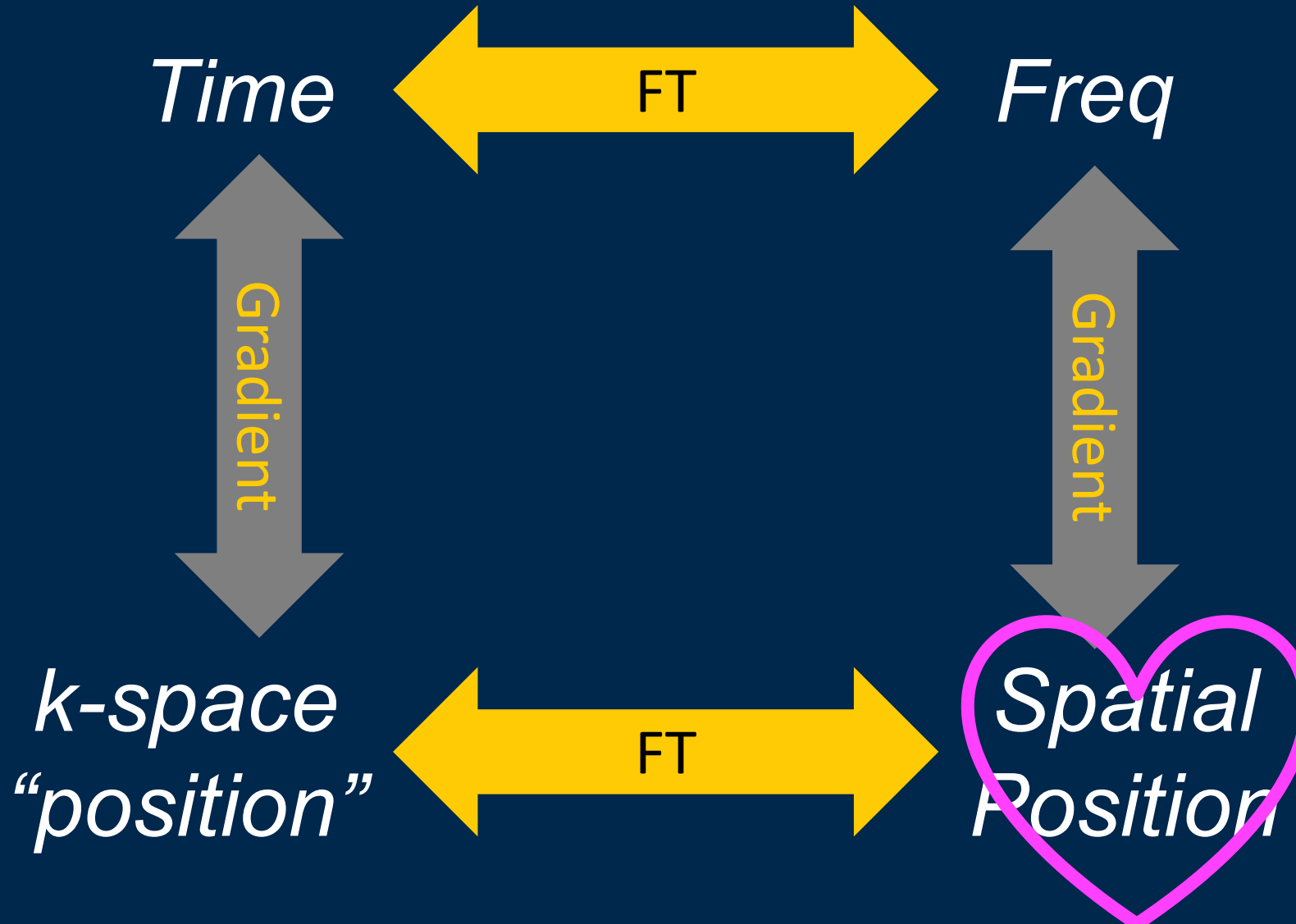
$$k_x = \gamma(B_0 + G_x)t$$

$$k_y = \gamma(B_0 + G_y)\tau$$

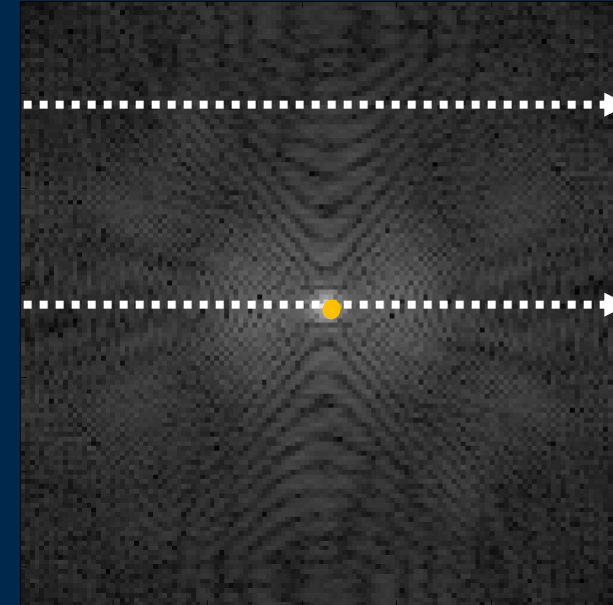
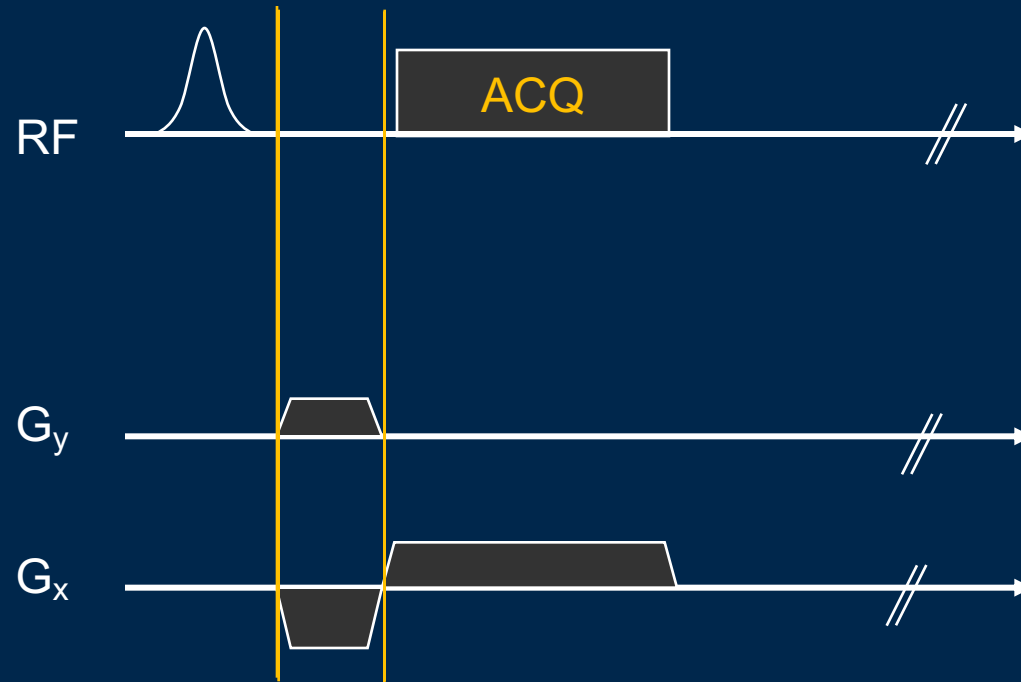
$$S(k_x, k_y) = \iint \rho(x, y) \cdot e^{-ik_x \cdot x} \cdot e^{-ik_y \cdot y} dx dy$$

OMG, No

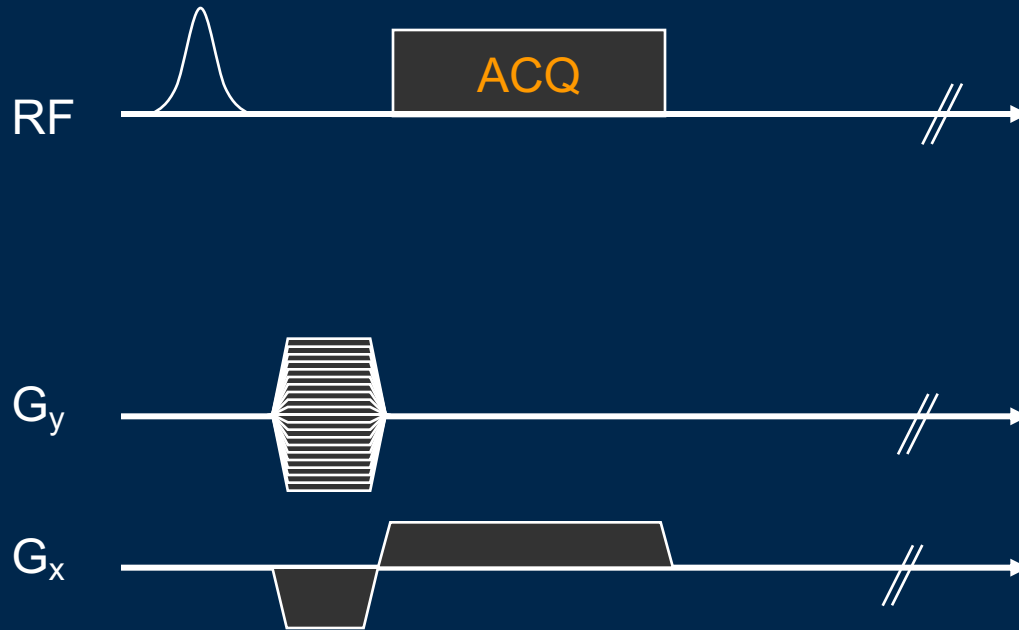
Signal measured in



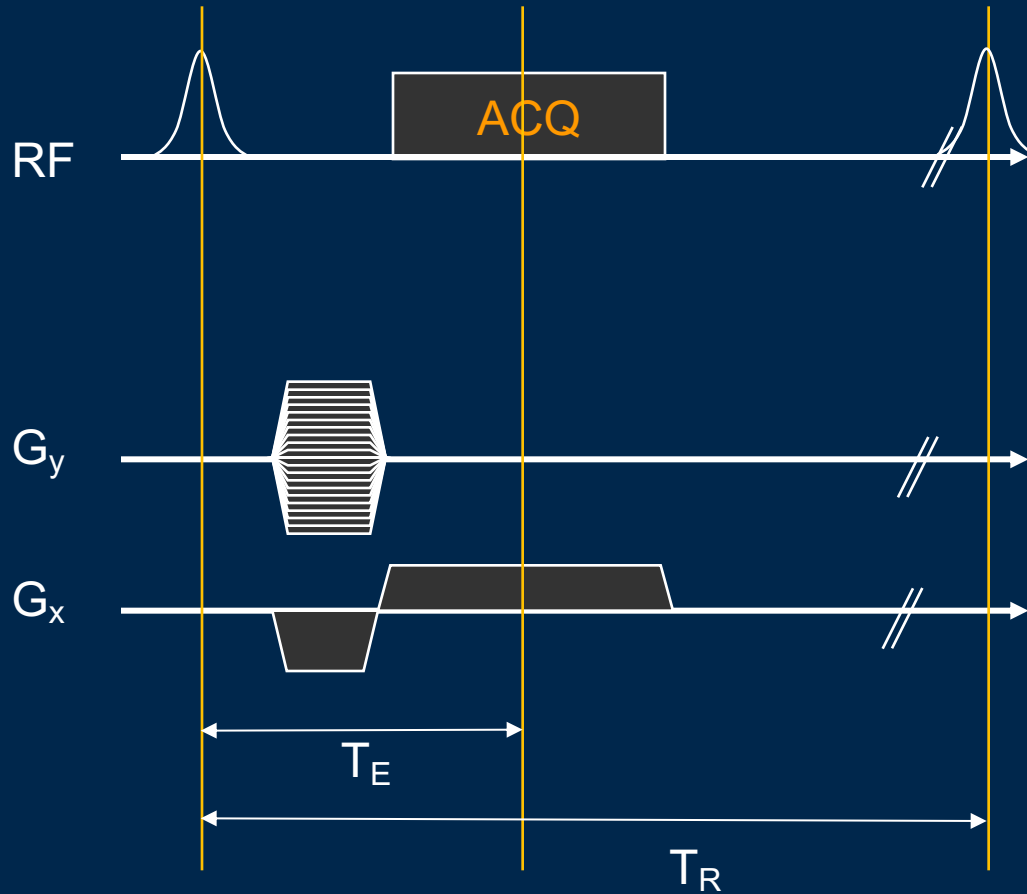
# Traversal of k-Space with Gradients



# Traversal of K-Space with Gradients



# Traversal of K-Space with Gradients



# Fundamental Imaging Time

$$Time = T_R \cdot N_{PE} \cdot NA$$

- $T_R$ : Amount of time needed to acquire one line (3 ms – 5 sec)
- $N_{PE}$ : Number of lines to acquire (32 – 512)
- $NA$ : Averages of each line (1 -  $\infty$ )



# Summary

- Magnetic field gradients used to link precession frequency to position → spatial encoding
- Frequency encoding: gradient on during data acquisition
- Phase encoding: gradient on to accumulate phase, then gradient *off* during data acquisition
- Application of gradients over time dictates k-space trajectory
- The need for multiple lines of k-space data leads to long acquisition times