Multivoxel pattern-based real-time fMRI

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Multivoxel pattern-based real-time fMRI

- Conceptual overview
- Experimental flexibility
- Practicalities and additional resources

Classification in Real Time



LaConte et al. Hum Brain Mapp (2007)

Conceptual overview

Supervised-learning rtfMRI

- Enables experimental flexibility
- Embodies "MVPA"
 - Complements region-based approaches
 - Enables brain-state decoding
 - Is computationally ideal for rtfMRI

Supervised learning

Complements univariate approaches (Friston, 1995; McIntosh, 1996; Strother, 2002; Moeller and Habeck 2006) Early demonstrations (Lautrup, 1994; Dehaene, 1998) Methodology and validation (Strother, 2002; LaConte, 2003; Mitchell 2004) Representation of different classes of stimuli (Haxby, 2001; Cox and Savoy, 2003; Haynes & Rees, 2005; Kamitani & Tong 2005) Detecting and tracking cognitive states (Polyn, 2005) Natural representation for real-time fMRI (LaConte, 2007; Shibata, 2011; deBettencourt, 2015)

Brain State Classification



Classification



Linear Discriminant Analysis



Linear Discriminant Analysis

time

X

voxels

Data Matrix:

PCA via SVD:

 $\mathbf{U}^{\mathrm{T}}\mathbf{X} = \Lambda\mathbf{V}^{\mathrm{T}} = Z$

Truncate Q (model complexity)

CVA:

$$\mathbf{C} = \mathbf{L}\mathbf{Z}^* = \mathbf{L}\mathbf{U}^{\mathrm{T}*}\mathbf{X}$$

Columns of L are determined by the eigenvectors of W⁻¹B. W is the within class variance and B the between class variance, and both are obtained from Z.

Support Vector Machine



SVM $D(\vec{z}_t) = (\vec{w} \cdot \vec{z}_t) + w_0$ minimize $\xi_t + \frac{1}{2} \|\vec{w}\|^2$ t=1

This term allows some training errors.

This term favors the widest possible margin,

C = infinity is hard margin SVM (as apposed to soft margin) because it does not allow any training errors

Nonlinear Decision Boundary



Multi-class

4-Class Model

Individual 2-class models





Temporal Regression



Predicting Network Time Series



Craddock, R.C. et al. OHBM 2012.

Pattern-based rtfMRI



Pattern-based rtfMRI



LaConte, et al. (2007) Hum Brain Mapp. 28: 1033-1044

Network configuration





Intensity (brightness) of a single pixel, changing during stimulus conditions

Controller interface for some display parameters





he AFNI interface



Slide provided by Ziad Saad

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Flexibility of brain state classification

With the exact same experimental setup (different instructions), subjects can learn to move the arrow



LaConte, et al. (2007) Hum Brain Mapp

Experimental flexibility: Task appropriate interfaces

Cigarette craving

| | 0 | |
|-------|---|----------------|
| | | |
| crave | | don't crave |

Covert counting rate



In collaboration with Pearl Chiu

Experimental flexibility: Support vector regression of RSNs

neurofeedback

controling events





Experimental flexibility: Brain Machine Interfaces



with Shashank Priya and Read Montague

Experimental flexibility: Brain Machine Interfaces



Support Vector Machine Maps of Real-Time Tasks \bullet FAST Z=0 Z=31 Z=8 X=-5 Y=15 Crave vs. Don't Crave Right vs. Left Tapping Fast vs. Slow Counting

Do feedback runs differ from nofeedback runs?





Speech: Covert counting Classification accuracy



Papageorgiou, et al. PNAS, 2013.

Speech: Covert counting



z=3

x=48

z=41

Papageorgiou, et al. PNAS, 2013.





Low accuracy subjects

With Feedback

Without Feedback

High accuracy subjects

With Feedback

Without Feedback

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Computational considerations

First real-time FMRI (Cox et al., 1995), developed a recursive partial correlation algorithm.

$$\rho = \frac{(\mathbf{P}\mathbf{r})^T(\mathbf{P}\mathbf{x})}{|\mathbf{P}\mathbf{r}| \cdot |\mathbf{P}\mathbf{x}|} = \frac{\mathbf{r}^T \mathbf{P}\mathbf{x}}{(\mathbf{r}^T \mathbf{P}\mathbf{r} \cdot \mathbf{x}^T \mathbf{P}\mathbf{x})^{1/2}} \quad \alpha = \frac{\mathbf{r}^T \mathbf{P}\mathbf{x}}{\mathbf{r}^T \mathbf{P}\mathbf{r}}.$$
 [2]

Equation [2] is not well suited for real-time FMRI...As the number of images grows (i.e., as the vectors increase in dimension), the amount of calculation will grow. In a real-time application, this is unacceptable, because at some point the computer will not be able to finish processing a new image before the next one is ready.

Computational considerations

- Real-time classification
 - Train with a deterministic algorithm
 - Training is computationally intensive but highly doable
 - Converge "immediately" after scan
 - Classify on an image-by-image basis

Basic Benchmarks



- Classifier safety factor > 20,000x.
 Approximately 1µsec / dot product.
- Network/AFNI Transfers > 20x volumes
 - Approximately 100 µsec / slice to transfer

3dsvm Plugin Screenshot Support Vector Machine Analysis

| Real-time | | | | | | | | | |
|------------------|-----|---|---------------------|-----------------|---------------------|-------------|----------|--|--|
| Training | | AFNI Plugin: Set Real-Time Options for 3dsvm - An AFNI SVM-Light Plugin | | | | | | | |
| | | | Run+Keep | | Run+Close | | Help | | |
| | _ | | | | | | | | |
| 🗖 Train Params | | Туре | classification 🗖 | | | | | | |
| | | Labels | -Choose Timeseries- | Censors | -Choose Timeseries- | | | | |
| | | Mask | — Choose Dataset — | с | V 🔺 1000 | Epsilon | V 🔺 🚺 🕹 | | |
| Model Output | | Kernel | linear 🗖 | poly order (d) | ▼ ▲ 3 | rbf ganna (| g) 🔽 🔺 🚺 | | |
| Model Inspection | | Prefix | | | | | | | |
| | ion | FIM Prefix | | Alpha Prix (,1D | | | | | |
| LTesting | | | | | | | | | |
| Test Data | | Model | — Choose Dataset — | | | | | | |
| | | Ib | | PORT | | | | | |
| | | Prefix (.1D) | | | | | | | |
| Predictions | | | | | | | | | |
| r | | | | | | | | | |

3dsvm



LaConte Lab

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3dsvm - an SVM-Light plugin for AFNI

description | interactive screen shot | download info | data and use todo | developers | reference

description

3dsvm is a command line program and plugin for AFNI, built around SVM-Light. It provides the ability to analyze functional magnetic resonance imaging (fMRI) data as described in (LaConte et al., 2005)

Features

- Reading AFNI-supported binary image formats
- Masking of variables (brain pixels)
 Censoring training samples
- Censoring training samples
 Visualizing alohas as time series and linear weight vectors as functional over
- Classifying multiple categories

Supervised learning of fMRI with 3dsvm can be used for predicting brain states to enhance our understanding of brain systems, complementing the conventional emphasis on spatial mapping. The figure below classification formalism used by 3dsvm. For each time point, the brain voxel intensibles can be represented in a high-dimensional vector space. During an fMRI experiment, each image is a point in the vector sp of these points, a classification model can be estimated to distinguish between experimental states. After the model is determined, independent data can be assigned a class membership.



- 3dsvm is a command line program and plugin for AFNI, built around SVM-Light. It provides the ability to analyze functional magnetic resonance imaging (fMRI) data as described in (LaConte et al., 2005)
- lacontelab.org/3dsvm.html

| | Alpha Profix (.1D) | |
|--|--------------------|--|
| | | |
| | | |
| | | |
| | | |
| | | |

3dsvm features

- Distributed with AFNI
- Reading AFNI-supported formats (including NIfTI)
 - Thus all preprocessing and data manipulation of the major software packages
- Masking of variables (brain pixels)
- Censoring training samples
- Visualizing alphas as time series and linear weight vectors as functional maps
- Multi-class classification
- Regression
- Support for non-linear kernels



3dsvm tour: basic steps

Prepare training and test data sets

- fMRI (3D+t)
- Labels (1D) labels for test data are optional (needed to to calculate accuracy)
- Mask for training data (3D) 3dsvm considers mask to be part of the model it generates
- 3dsvm training
 - Creates a model that can be tested with independent data
 - For convenience, inspecting the model
 - Model alphas (1D)
 - Weight vector map (3D)
- 3dsvm testing
 - Calculates class and/or distance measure for each new timepoint
 - Prediction accuracy (if test set labels are available)

3dsvm Plugin Snapshot Support Vector Machine Analysis

| | AFNI Plugin: 3dsvm – An AFNI SVM Light Plugin | | | | | |
|----------|---|------------|---------------------|----------------|---------------------|------------------------------|
| | Quit | | Run+Keep | | Run+Close | Help |
| | Training | | | | | |
| | 🗍 Train Data | Dataset | Choose Dataset | Labels | -Choose Timeseries- | Censors - Choose Timeseries- |
| training | 🔲 Train Params | Mask | Choose Dataset | Kernel | Linear 🗖 | C 🔽 🖌 🚺 100 |
| | Model Output | Prefix | | | | |
| | Model Inspection | FIM Prefi> | × [] | Alpha Prefix (| .10) | |
| | Testing | | | | | |
| testing | 🗖 Test Data | Dataset | — Choose Dataset — | Moxle1 | — Choose Dataset — | I |
| testing | 🗌 Label Output | Prefix (.1 | (0) | | | |
| | ☐ 'True' Labels | File | -Choose Timeseries- | | | |

Command Line

Training - 3dsvm -trainvol run1+orig \ -trainlabels run1_categories.1D \ -mask mask+orig \ -model model_run1

Testing - 3dsvm -testvol run2+orig \ -model model_run1+orig \ -predictions pred2_model1

Left vs. Right visual stimulus



Left vs. Right visual stimulus



Left vs. Right visual stimulus



Left vs. Right visual stimulus



Bimanual coordination task:

Feedback of both the left and right hand performance was provided by a four arc display described in (Klaiman and Karniel, 2006), where button tapping was used to move the inner arches to match the speed of the outer arches.



1:1 – Good Performance

1:1 – Poor Performance







3:2 – Good Performance

3:2 – Poor Performance

Group brain maps of the SVM models for the 14 subjects



first two TRs have been removed for each transition between stimuli.

#!/bin/csh
example by Prashant Prasad

3dsvm -trainvol volreg_run1_PPA+orig \
 -trainlabels LABEL_PPA_1.1D \
 -mask automask_run1_PPA+orig \
 -bucket bucket_run1_PPA \
 -model model_run1_PPA

3dsvm -classout \ -testvol volreg_run2_PPA+orig \ -testlabels LABEL_PPA_2.1D \ -model model_run1_PPA+orig \ -predictions pred_run2_frmRun1_classout

#!/bin/csh
example by Prashant Prasad

3dsvm -trainvol volreg_run1_PPA+orig \
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3dsvm -testvol volreg_run2_PPA+orig \ -testlabels LABEL_PPA_2.1D \ -model model_run1_PPA+orig \ -predictions pred_run2_frmRun1



ex<u>ample</u>2

#!/bin/csh
example by Prashant Prasad

3dsvm -trainvol volreg_run1_PPA+orig \
 -trainlabels LABEL_PPA_1.1D \
 -mask automask run1 PPA+orig \
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 -testvol volreg_run2_PPA+orig \
 -testlabels LABEL_PPA_2.1D \
 -model model_run1_PPA+orig \
 -predictions pred_run2_frmRun1_classout

3dsvm -testvol volreg_run2_PPA+orig \ -testlabels LABEL_PPA_2.1D \ -model model_run1_PPA+orig \ -predictions pred_run2_frmRun1

1:1 vs. Fixation (93% Accuracy) 3:2 vs. Fixation (93% Accuracy) 1



Demonstration Experiment

Initial scans

• Localizer (9 seconds)



• Anatomical scan (4.5 minutes)



LaConte, Neurolmage (2011)

fMRI runs

• Masking run (10 seconds)



• Training run (6 minutes)



• Feedback run (6 minutes)



Setting up AFNI's RT plugin

• Manually

- Good for learning and demo

| 00 | 90 | | | 🔀 [A] RT Opt | ions | | | | |
|----------|--------------|--------|---------------|--------------|-----------------|------|----------|-----------|---|
| | | AF | NI Plugin: Se | et Real-Time | Acquisition Opt | ions | | | |
| | Quit | | Set+Kee | p 📃 | Set+Close | | | Help | |
| | Images Only | No 🗖 | | | | | | | |
| | Root | (| | | | | | | |
| | Update | 1 🗖 | | | | | | | |
| | Function | None 🗖 | | | | | | | |
| | Verbose | Yes 🗖 | | | | | | | |
| | Registration | Non | e 🗖 | Base Image | 3 🗖 | Resa | mpling 🛛 | Quintic 🗖 | Ξ |
| | Graph | No | F | NR [x-axis] | V A [100 | YR [| y-axis] | / 🔺 🚺 | |
| | Mask | Choos | se Dataset | Vals to Sen | d None 🗖 | | | | |
| | RT Write | Off | | Channe1Merg | e none 🗖 | | | | |
| <u> </u> | | | | | | | | | |

Slide provided by Ziad Saad

Setting up AFNI's RT plugin

• Via Environment Variables

setenv AFNI_REALTIME_Registration setenv AFNI_REALTIME_Graph 3D:_realtime Realtime

| 00 | 0 | | 🔀 [A] RT Options | |
|----|--------------|-----------------|------------------------------|----------------------|
| | | AFNI Plugin: Se | et Real-Time Acquisition Opt | ions |
| | Quit | Set+Keej | Set+Close | Help |
| Г | Images Only | No 🗖 | | |
| Г | Root | []_ | | |
| | Update | 1 🗖 | | |
| | Function | None 🗖 | | |
| | Verbose | Yes 🗖 | | |
| | Registration | 3D: realtime 🗖 | Base Image 3 🗖 | Resampling Quintic 🗖 |
| | Graph | Realtime 🗖 | NR [x-axis] 🔽 🔺 100 | YR [y-axis] 🔻 🔺 🚺 |
| | Mask | Choose Dataset | Vals to Send 🛛 None 🗖 | |
| | RT Write | 1 | ChannelMerge none 🗖 | |
| | | | | |

Slide provided by Ziad Saad

AFNI help resources

- Readme files
 - README.driver
 - README.environment
 - README.realtime
- Demo material available on: http://afni.nimh.nih.gov
- Automation
 - @DriveAfni script
 - @DriveSuma script
 - @DO.examples
- Sample programs
 - rtfeedme.c
 - Dimon.c
 - serial_helper.c
 - realtime_receiver.py

Multivoxel pattern-based real-time fMRI

- Conceptual overview
 - Supervised learning for fMRI
 - (classification and regression)
 - Integration with MRI and real-time platforms
- Experimental flexibility
 - Whole-brain models trained to the distributed patterns of each individual for neurofeedback, BCIs, adaptive fMRI paradigms, etc.
 - Feedback improves classifications
 - Employs frontoparietal networks
- Practicalities and additional resources
 - 3dsvm and AFNI's realtime plugin