

MRI Physics II(A): Understanding Phase Encoding

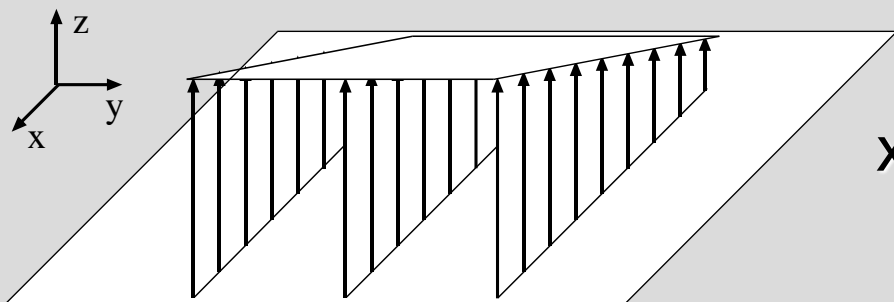
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Gradient Fields

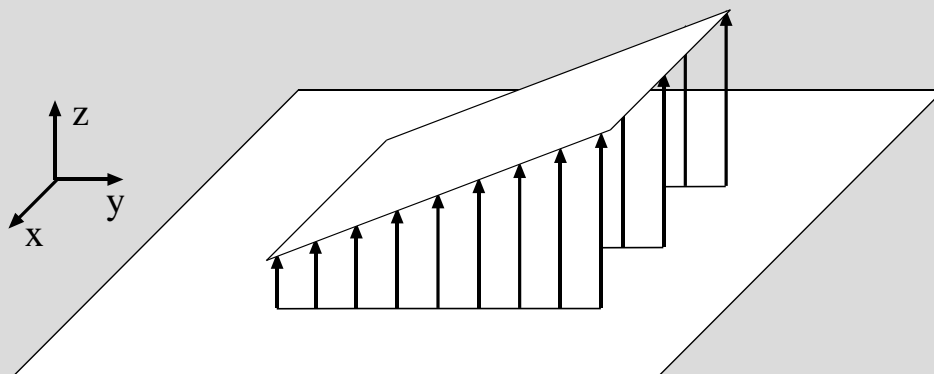
- The last magnetic field to be used in MRI are the gradient fields
 - 3 of them: G_x , G_y , G_z
 - These are for localization
 - Make the magnetic field different in different parts of the body, e.g. for the x-gradient:

$$B(x) = B_0 + G \cdot x$$

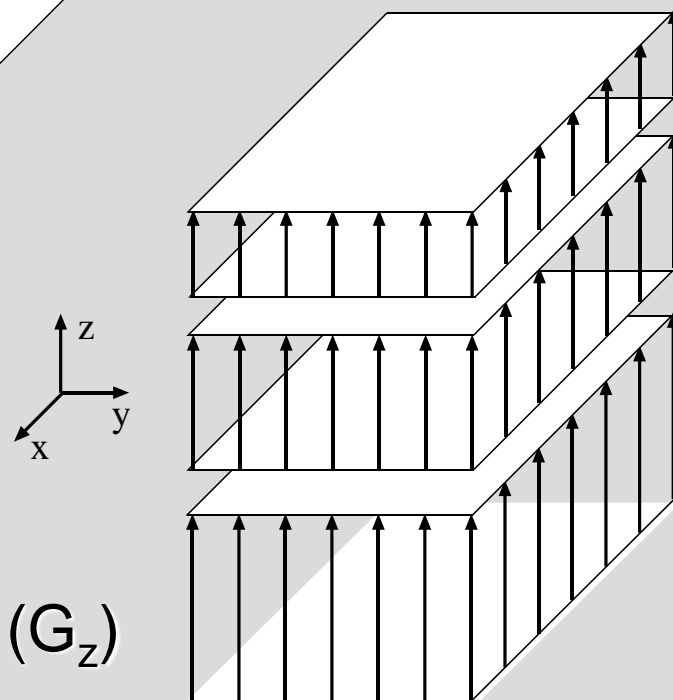
- Observe the field points in the same direction as B_0 so it adds to B_0 .



x-gradient (G_x)



y-gradient (G_y)



z-gradient (G_z)

Frequency Encoding

- A fundamental property of nuclear spins says that the frequency at which they precess (or emit signals) is proportional to the magnetic field strength:

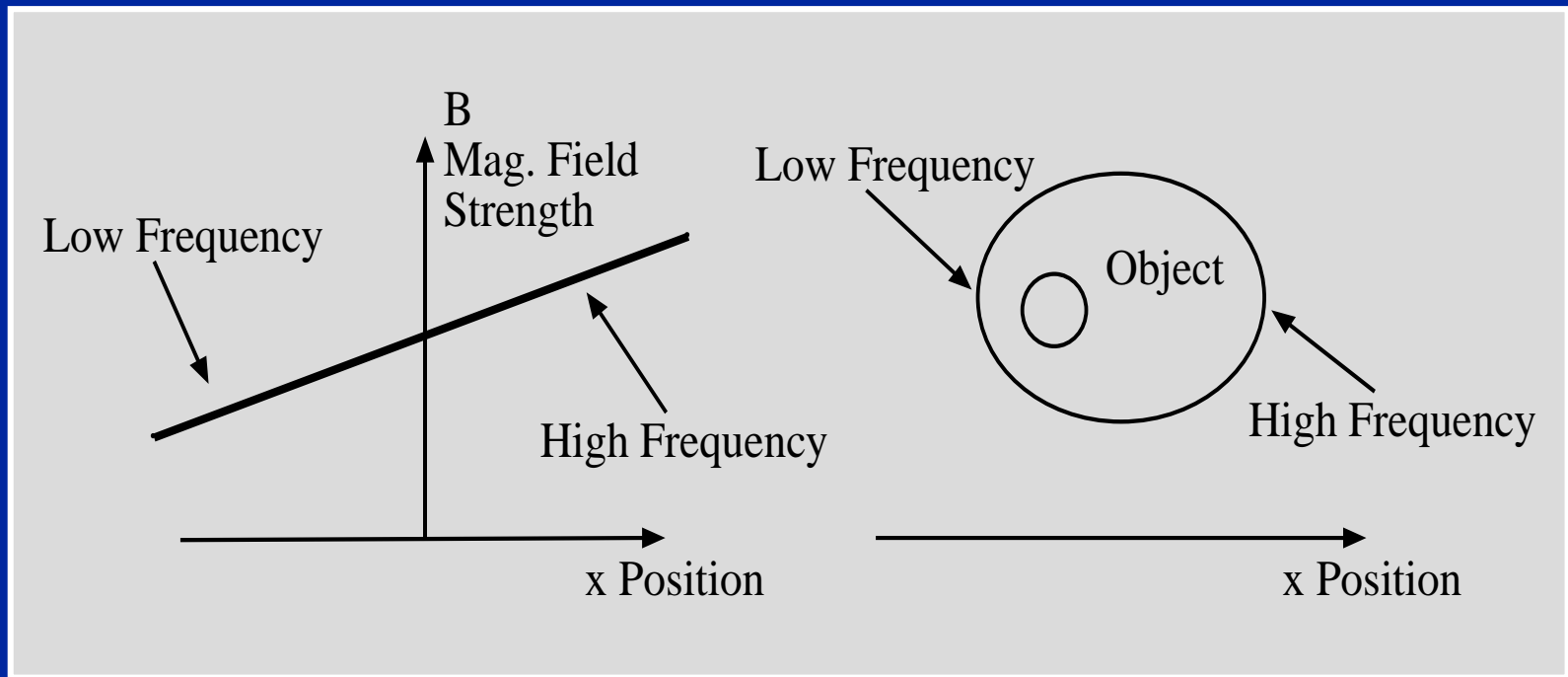
$$\omega = \gamma B$$

- The Larmor Relationship

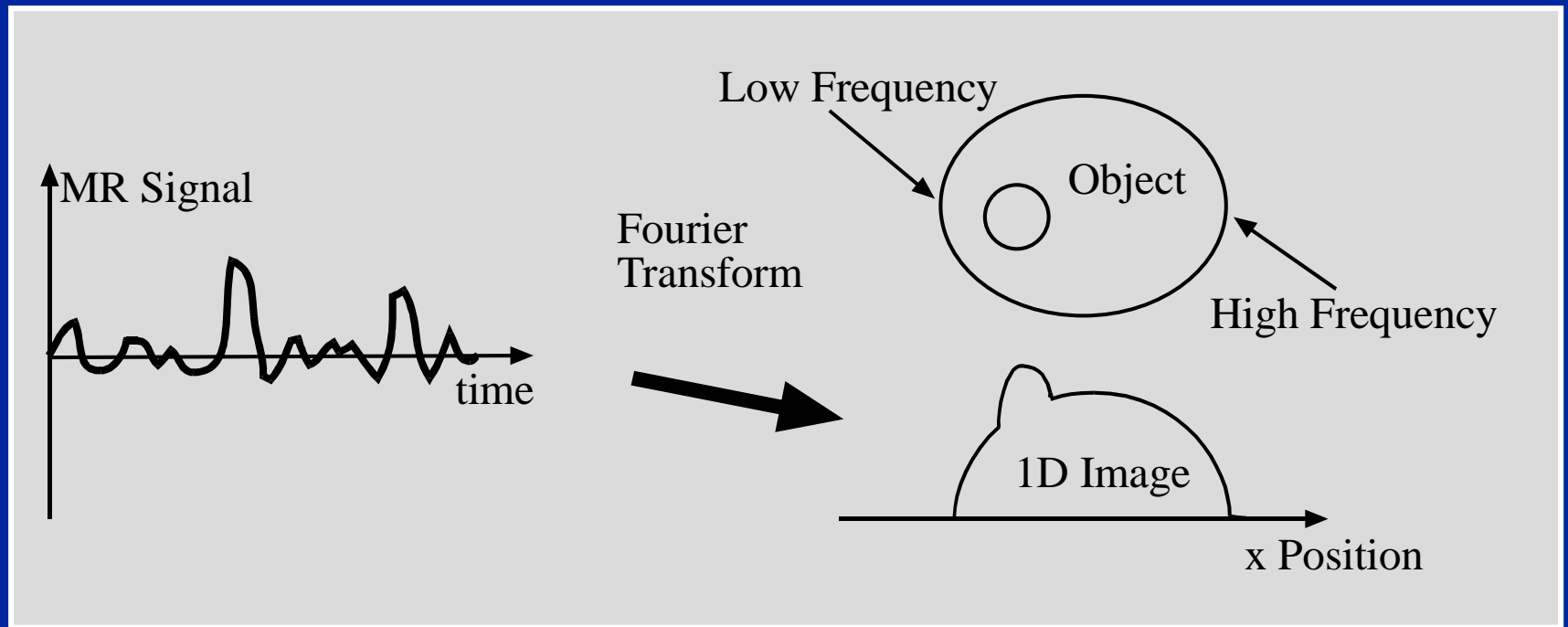
- This says that precession frequency now increases as we move along the x-direction (e.g. as we move rightwards).

$$\omega(x) = \gamma (B_0 + G \cdot x).$$

Frequency Encoding

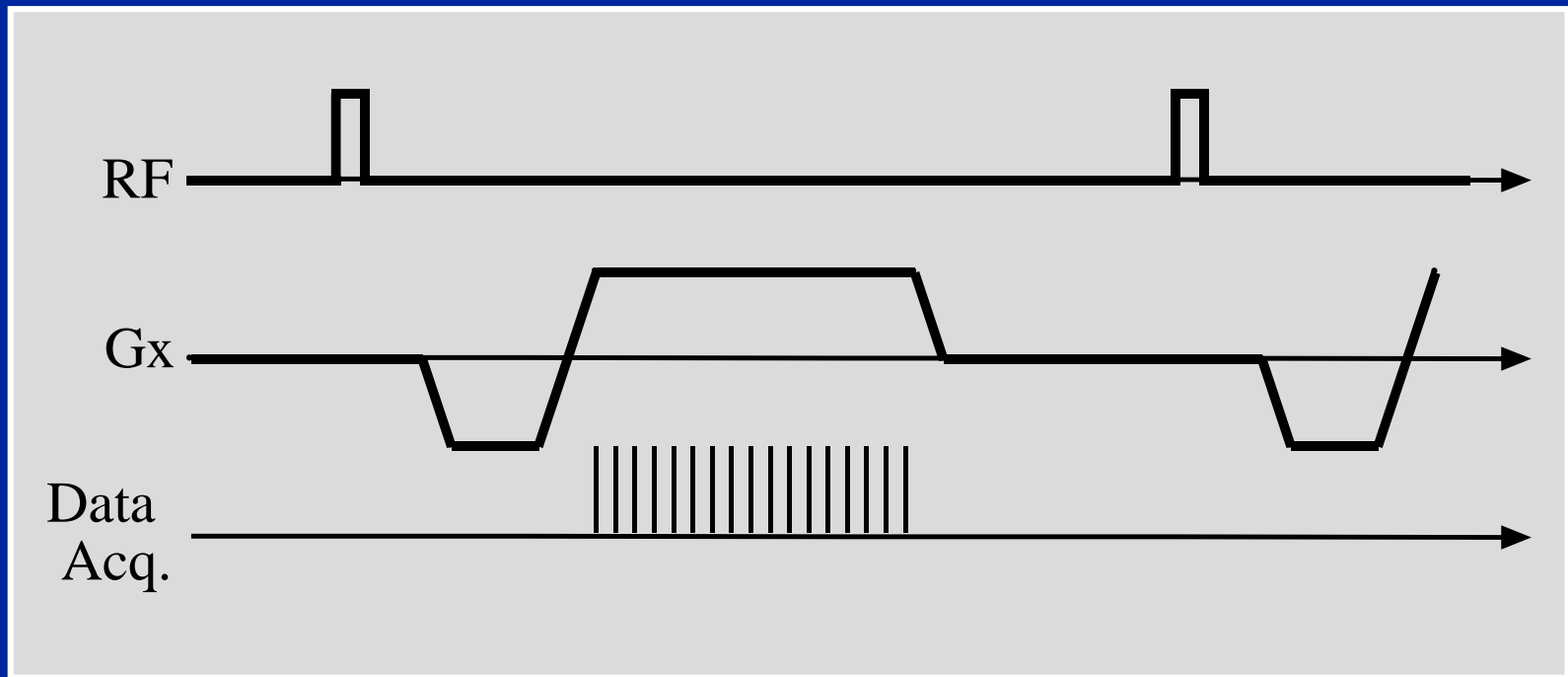


Fourier Transforms



1D Pulse Sequence

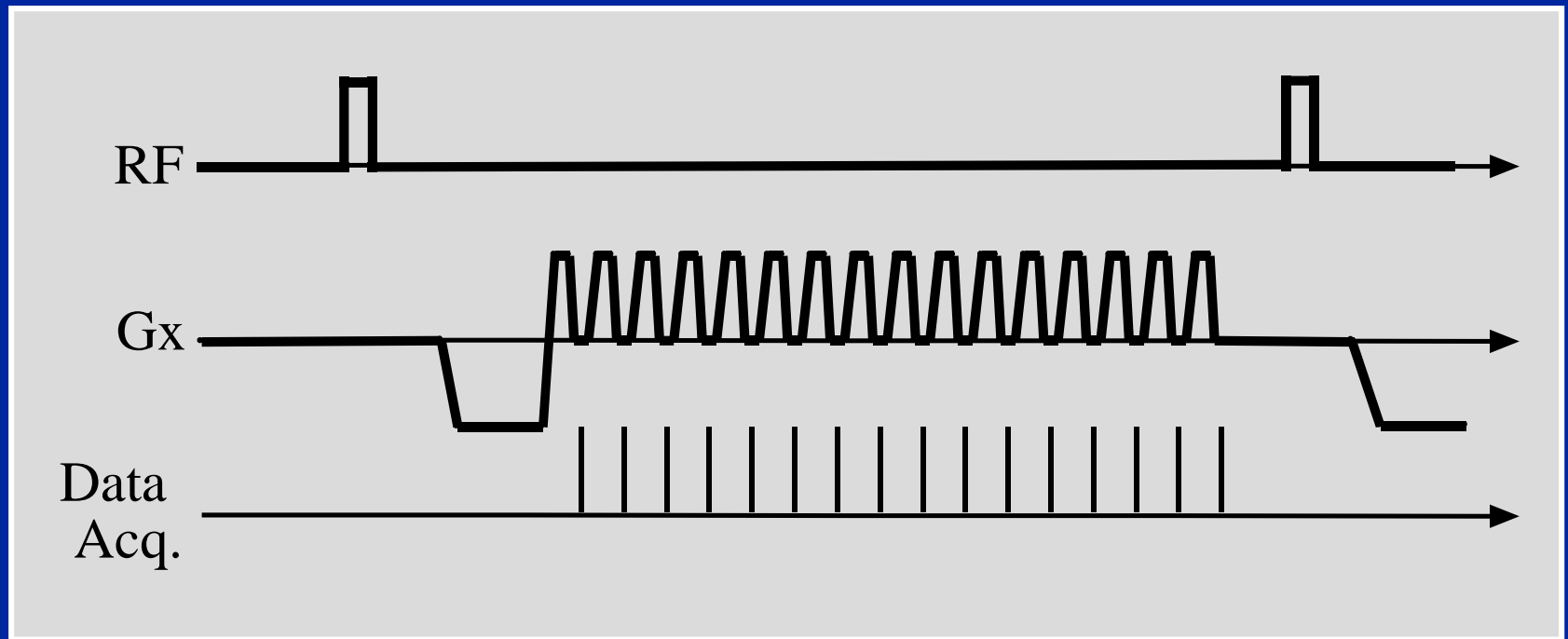
Now we put this together with excitation:



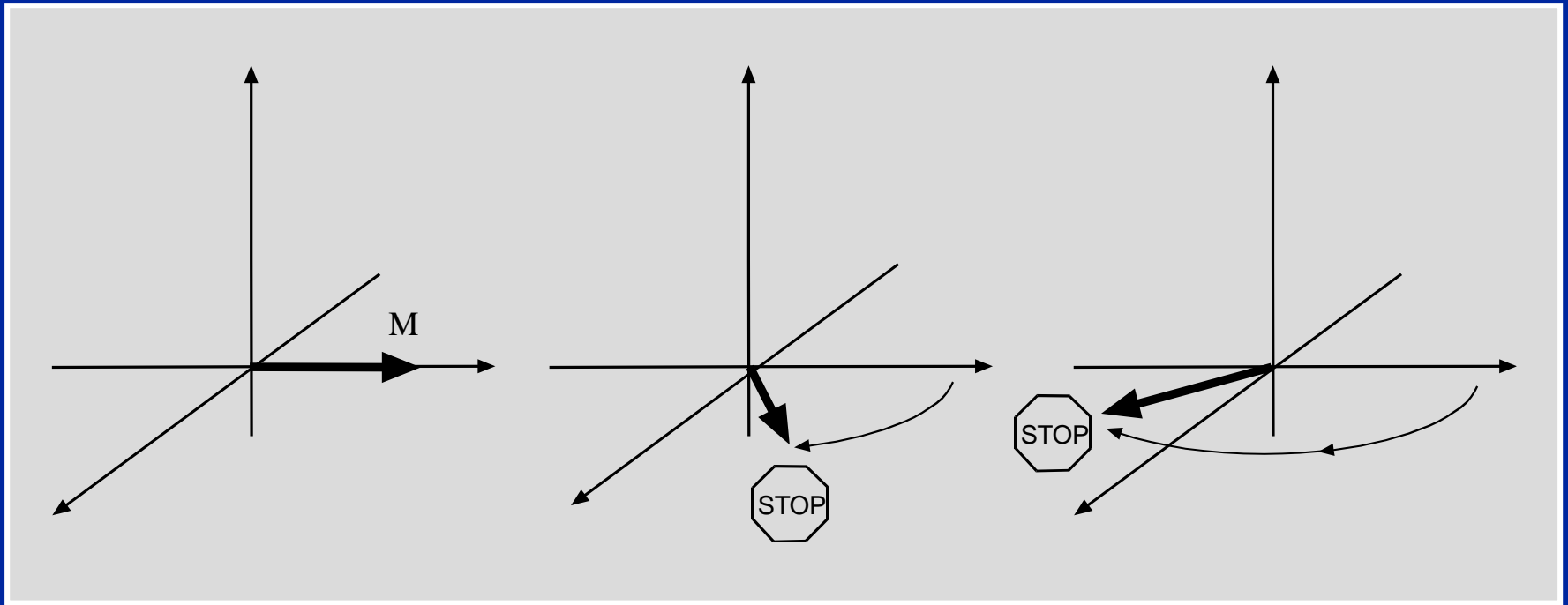
Alternate Method for 1D Localization

- In the case just described, the “frequency encoding” gradient was constant.
 - At different locations spins precessed at different frequencies.
 - This was true as long as the gradient was “on.”
- We now look at an alternate situation where the gradient is turned “on” and “off” rapidly.
 - At different locations spins will precess at different frequencies, but only during the times that the gradient is “on.”

Alternate Method for 1D Localization



Stop-Action Movement of Magnetization



Sample 1

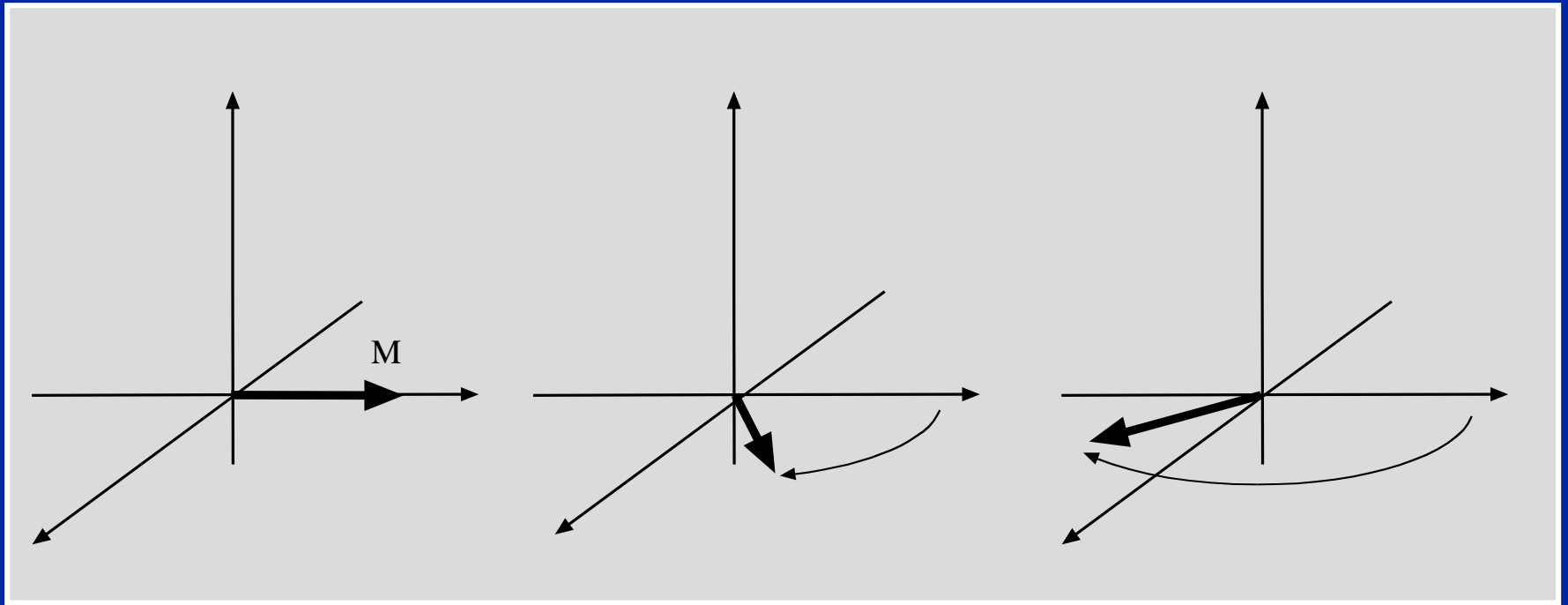
Sample 2

Sample 3

On/Off Gradients in 1D Localization

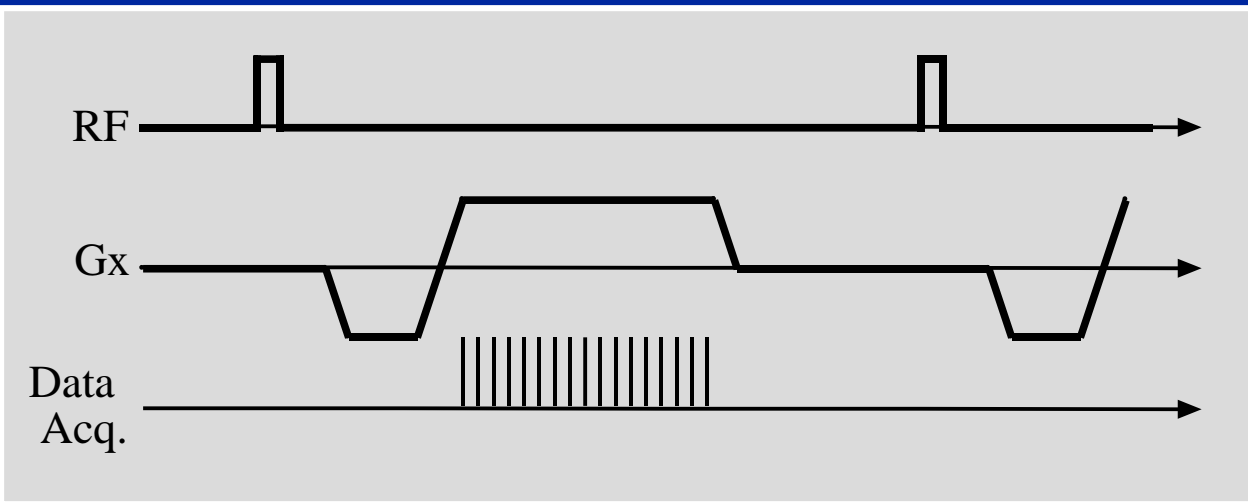
- In the case previously described, the spins precessed smoothly.
- In this case, the spins precess in a “stop-action” or jerky motion.
- What is different here is that we sample the MR signal while it has stopped precessing.
 - At each step, the spatial information has been encoded into the phase.
 - This is a form of “phase encoding.”

Movement of Magnetization with Constant Gradient

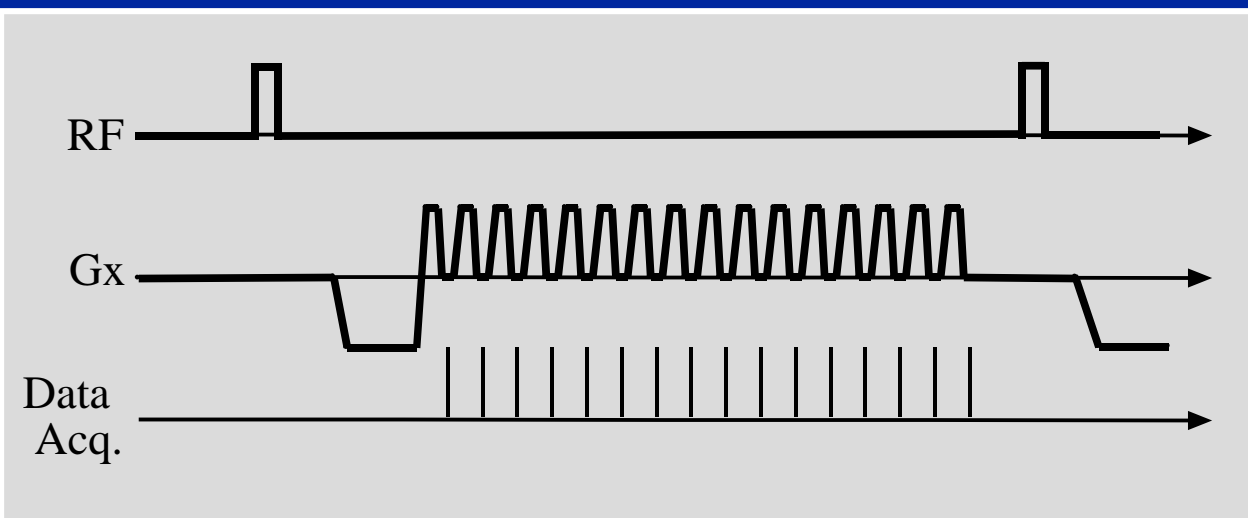


Smooth precession of magnetization

Different 1D Localization Methods

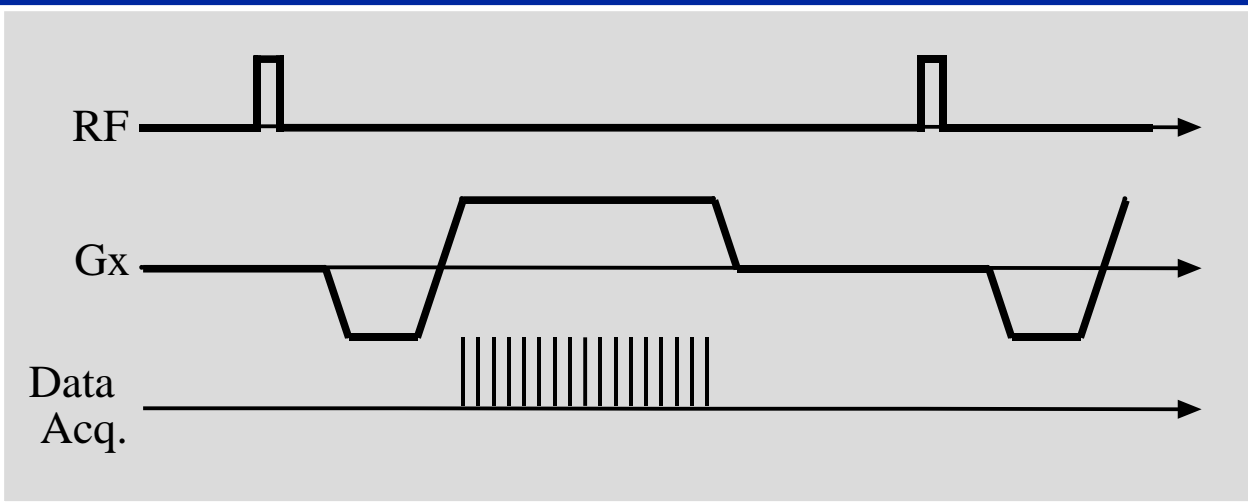


Upper - smooth precession at different frequencies.
(frequency encoding)



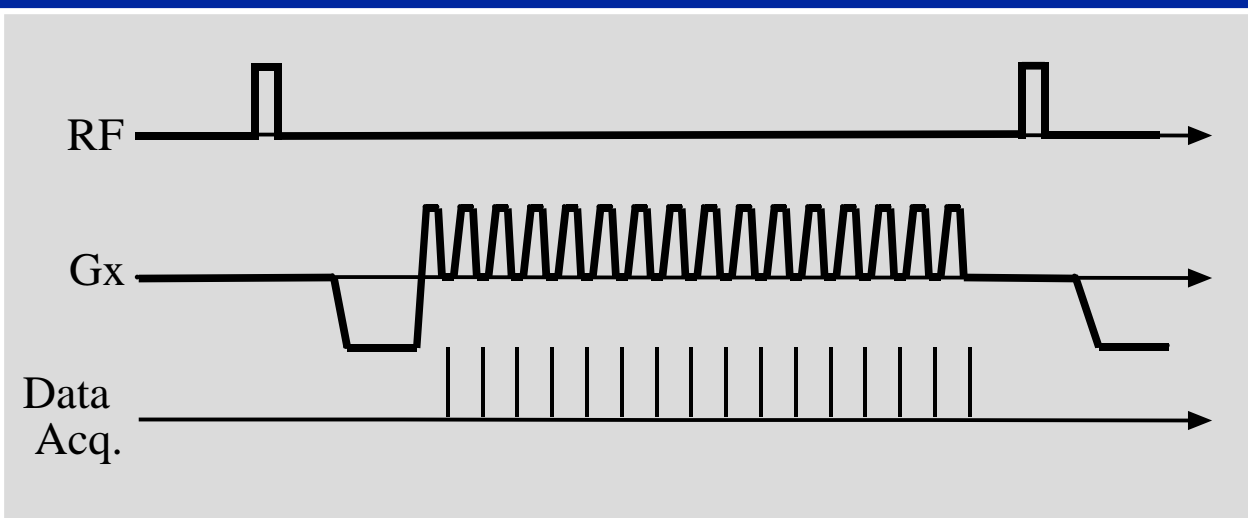
Lower - precession in small steps, phase contains location info.
(phase encoding).

Different 1D Localization Methods



Are the sampled data the same?

Yes, if we neglect T_2 .

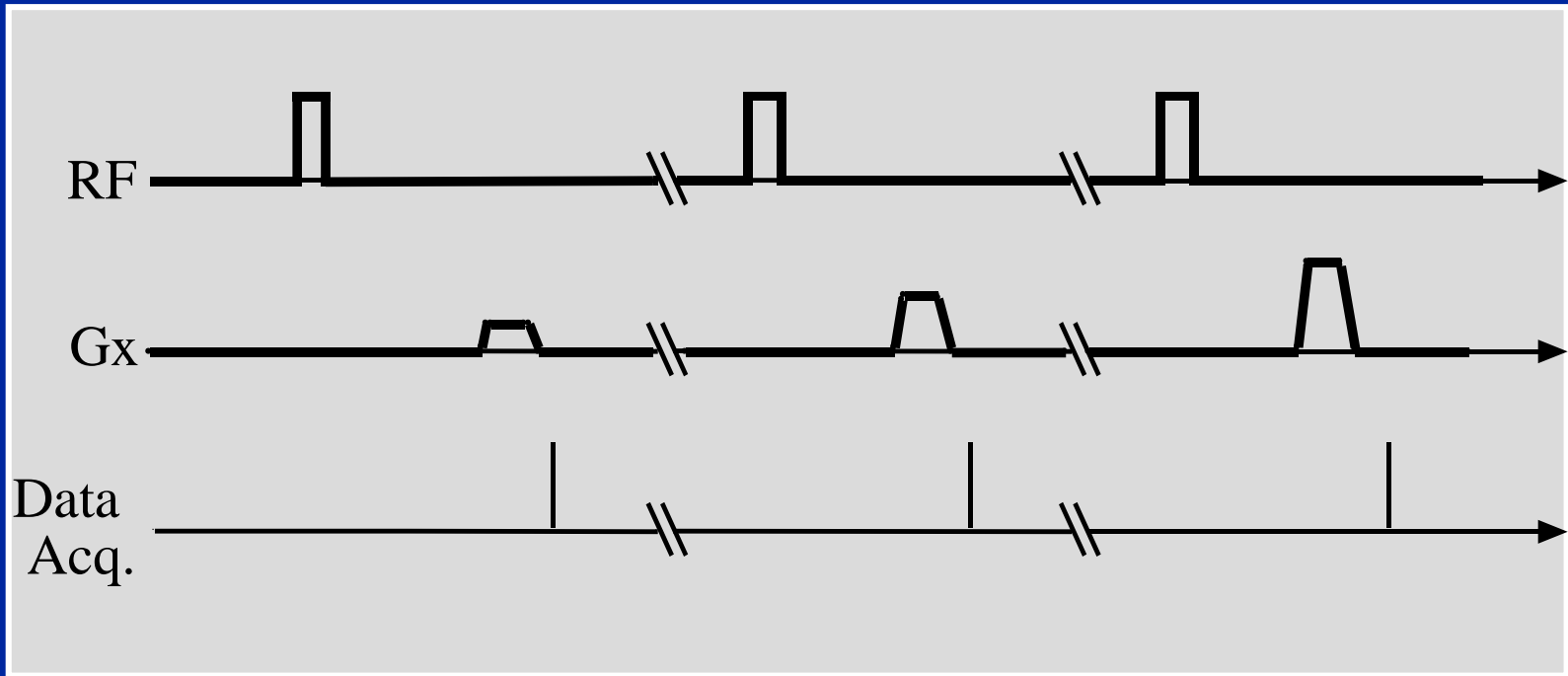


In both cases, the Fourier transform creates the 1D image.

Alternate Method #2 for 1D Localization

- In the above cases, gradients were turned on and samples were acquired following a single RF excitation pulse.
 - At different locations spins precessed at different frequencies.
 - Motion was either smooth or “stop-action.”
- We now look at a situation where a single sample is acquired after each RF pulse.
 - Spins precess for a particular length of time and then a single sample is acquired.

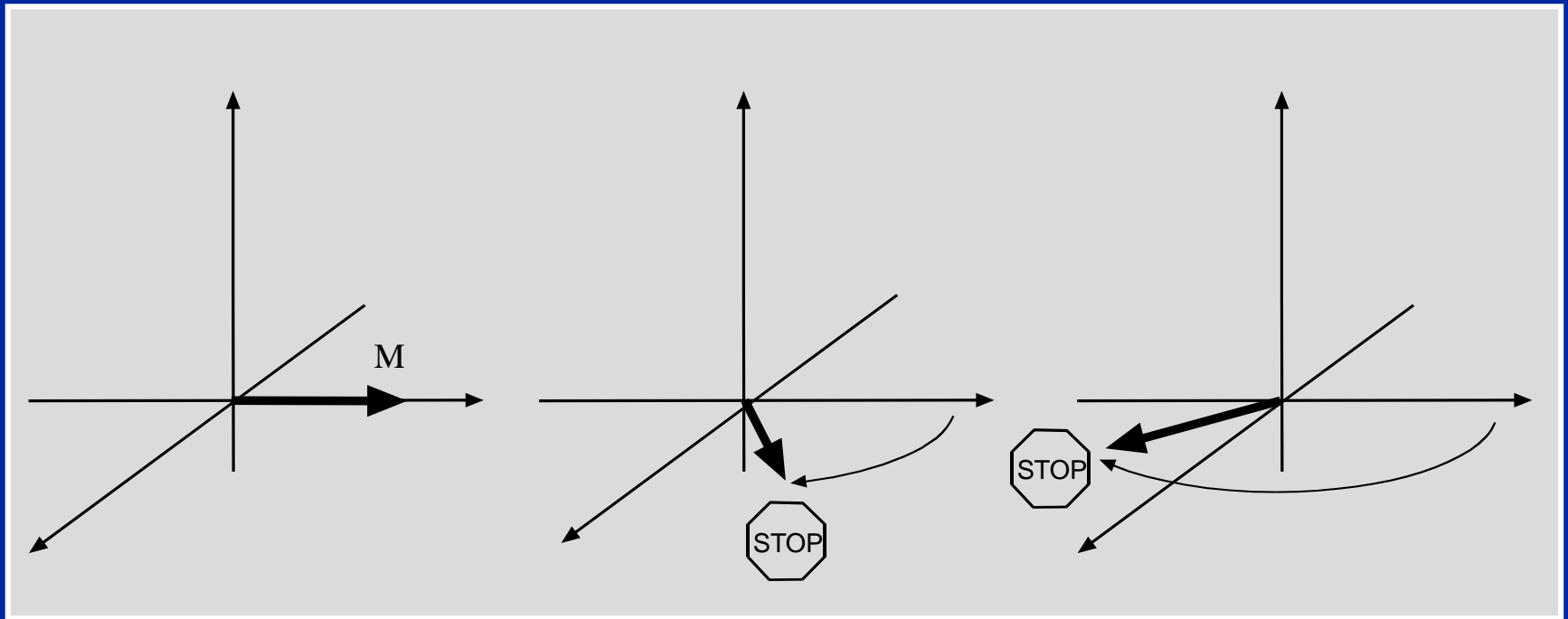
Alternate Method #2 for 1D Localization



Phase Encoding in 1D

- Again, spins precess only as long as gradient is turned “on.”
- If we look spins after each step (sample location), the precession will again appear as “stop-action” motion.
- Again, spatial information has been encoded into the phase of spin.
 - Another form of “phase encoding.”

Phase Encoding in 1D



Phase
Encode 0

Phase
Encode 1

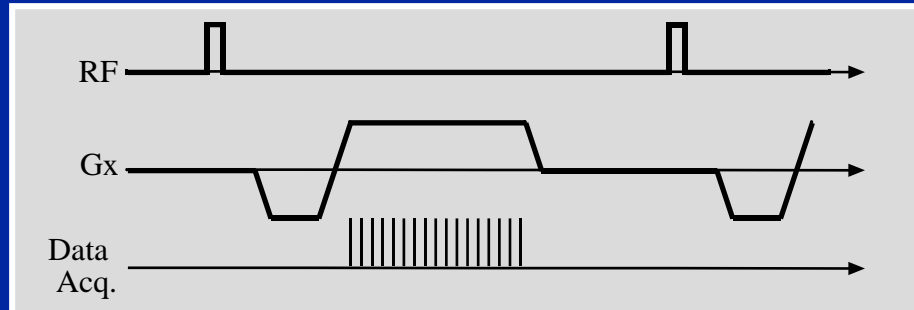
Phase
Encode 2

Three Methods for 1D Localization

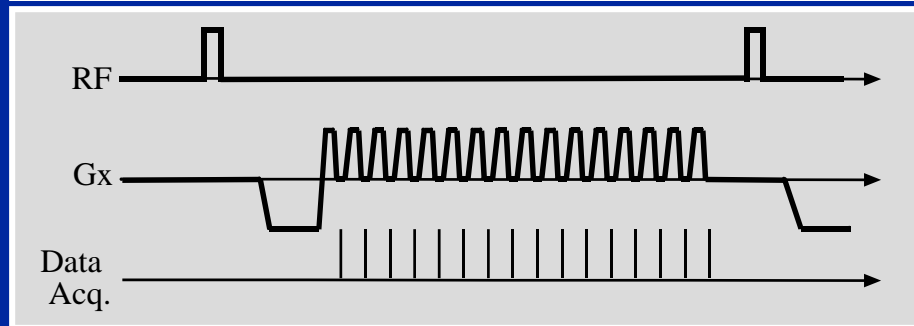
- 1D Localization:
 - Frequency encoding
 - Phase encoding following a single RF pulse
 - A single phase encode following each of many RF pulses
- Sampled data is the same (if we neglect T2).
- The Fourier transform creates the 1D image.

Three Methods for 1D Localization

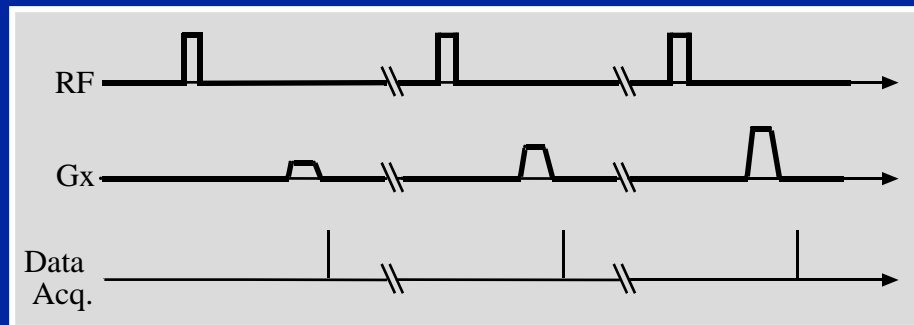
Frequency
Encoding



Phase
Encoding
Method #1



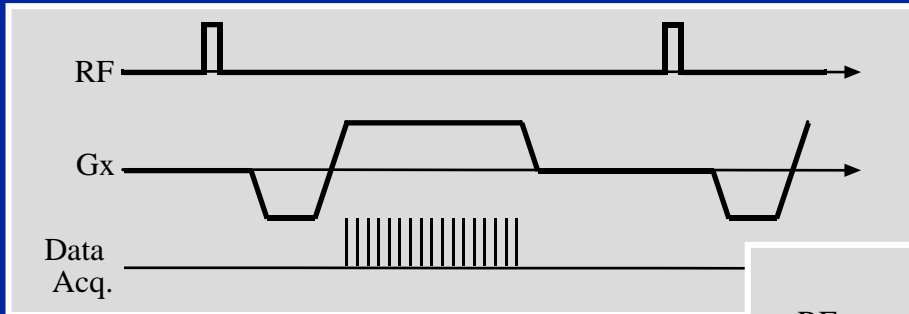
Phase
Encoding
Method #2



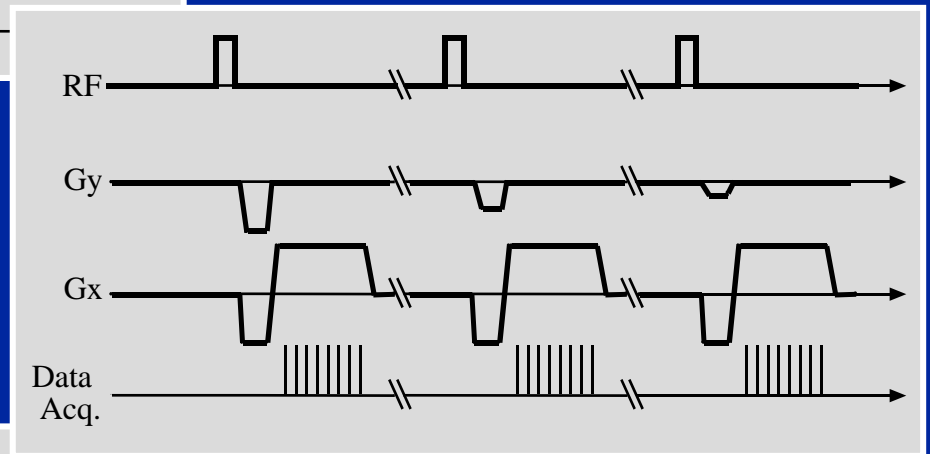
2D Localization

- In general, we will combine two 1D localization methods to create localization in two dimensions (2D).
- The spin-warp method (used in almost all anatomical MRI) is a combination of :
 - Frequency encoding in one direction (e.g. Left-Right)
 - Phase encoding in the other direction (e.g. Anterior-Posterior)

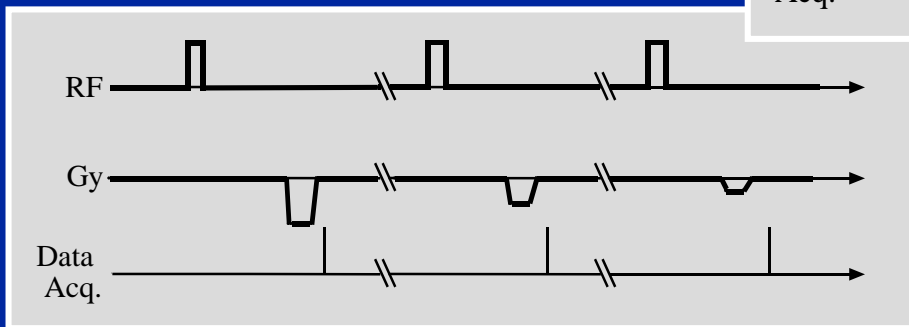
2D Localization - Spin Warp



Frequency Encoding
(in x direction)



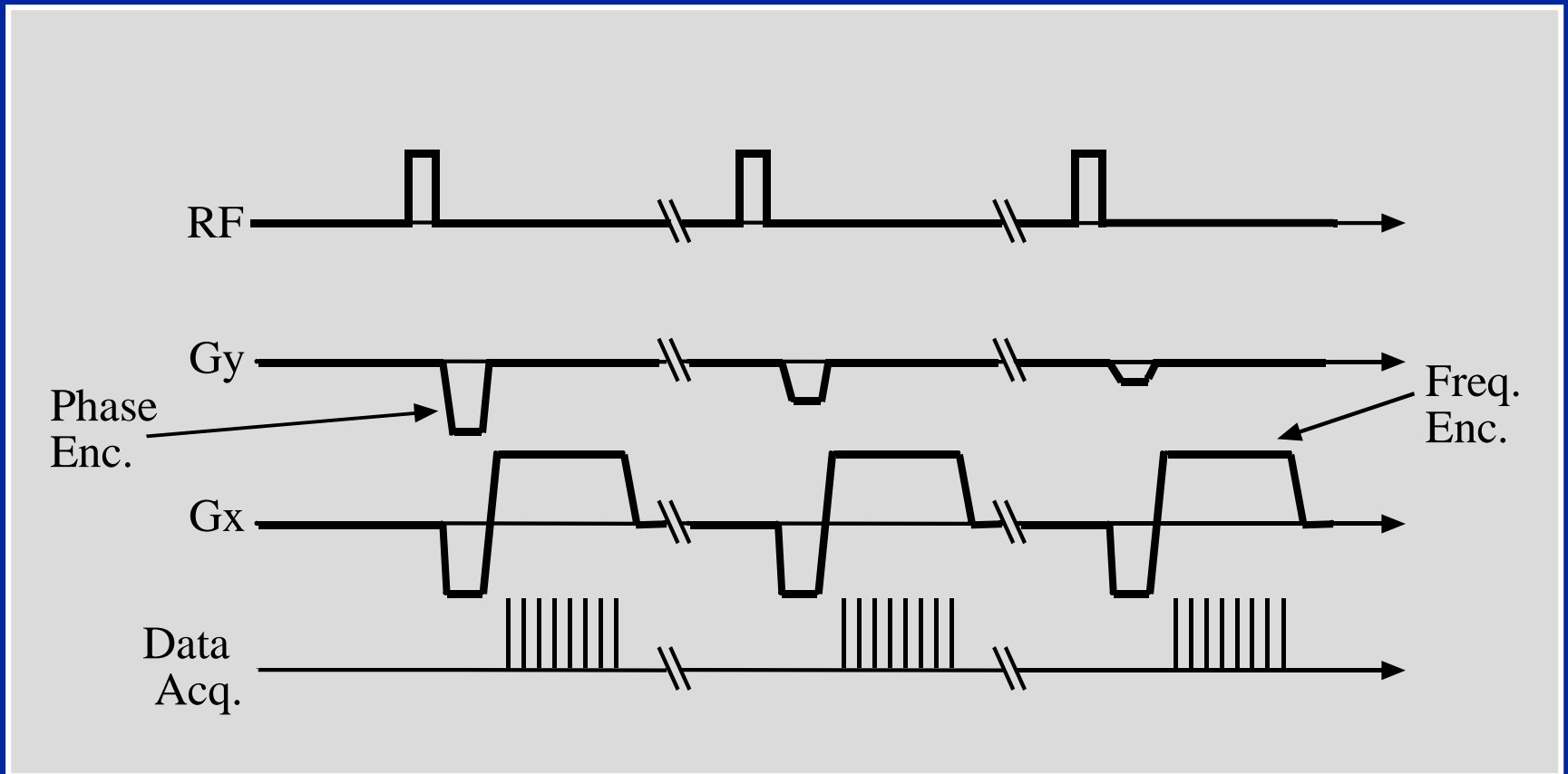
Phase Encoding
Method #2
(in y direction)



Spin-Warp Imaging

- For each RF pulse:
 - Frequency encoding is performed in one direction
 - A single phase encoding value is obtained
- With each additional RF pulse:
 - The phase encoding value is incremented
 - The phase encoding steps still has the appearance of “stop-action” motion

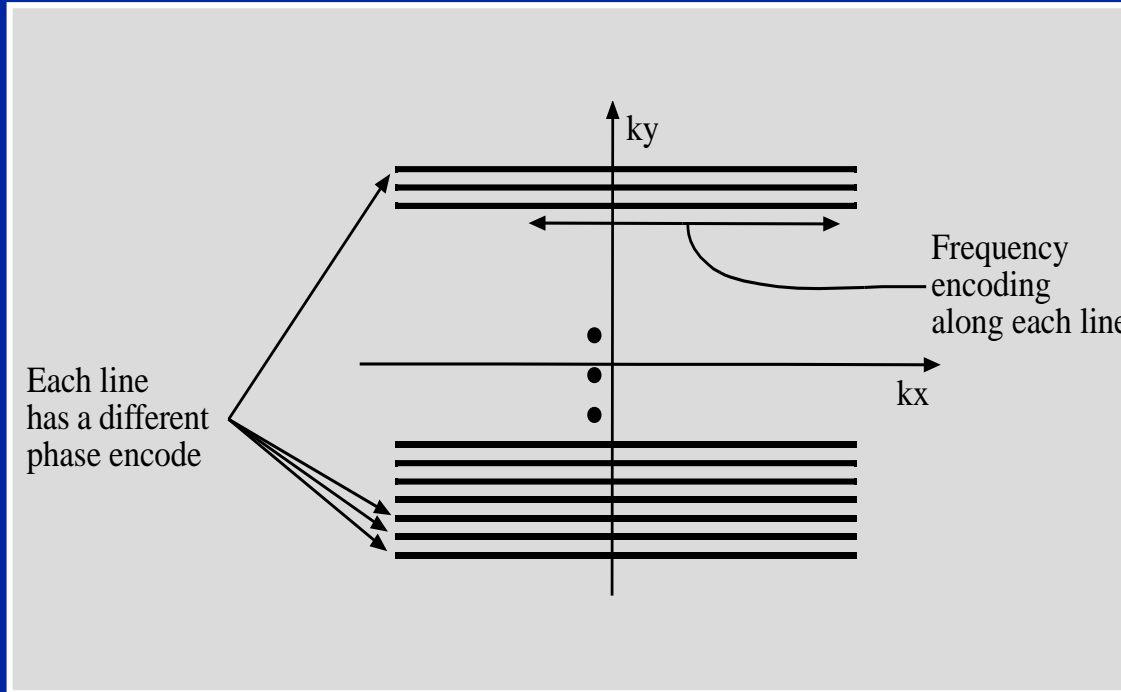
Spin-Warp Pulse Sequence



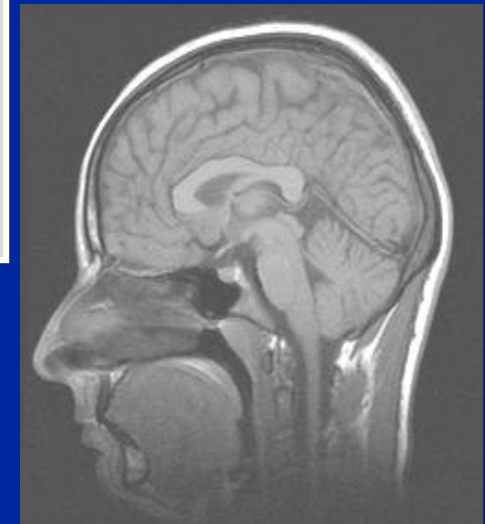
Spin-Warp Data Acquisition

- In 1D, the Fourier transform produced a 1D image.
- In 2D, the Fourier transform is applied in both the frequency and phase encoding directions.
 - This is called the 2D Fourier transform.
- Commonly we structure the samples in a 2D grid that we call “k-space.”
 - One line of k-space is acquired at a time.

Spin-Warp Data Acquisition



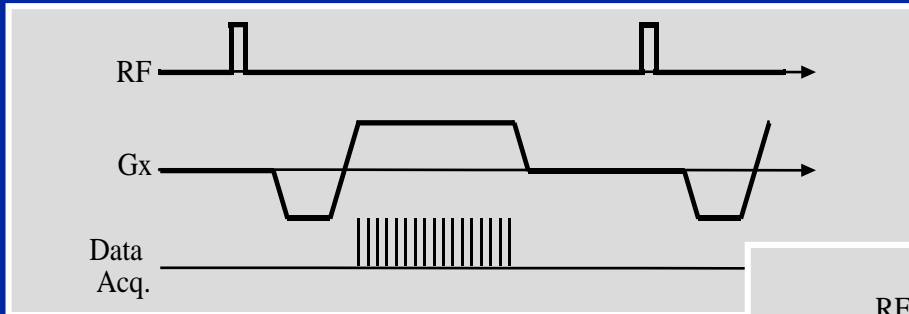
2D Fourier Transform



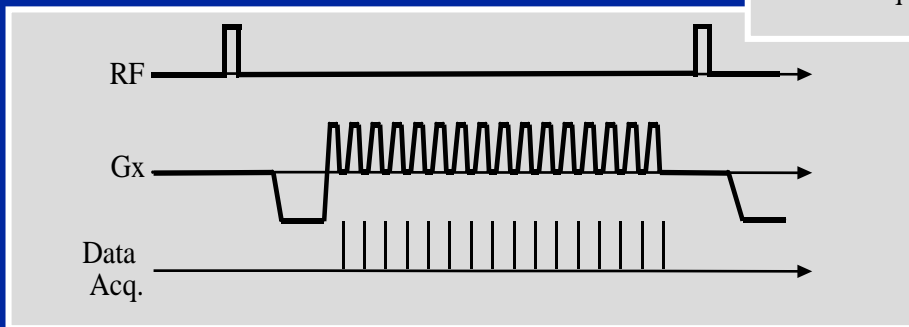
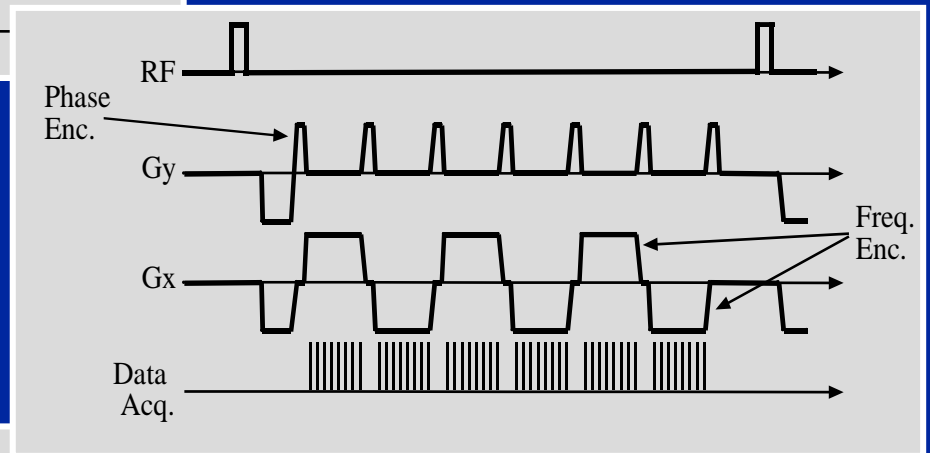
Echo-Planar Imaging

- As with spin-warp imaging, echo-planar imaging (EPI) is just the combination of two 1D localization methods
- EPI is also a combination of :
 - Frequency encoding in one direction (e.g. Left-Right)
 - Phase encoding in the other direction (e.g. Anterior-Posterior)
- EPI uses a different phase encoding method.

Echo-Planar Imaging



Frequency Encoding
(in x direction)

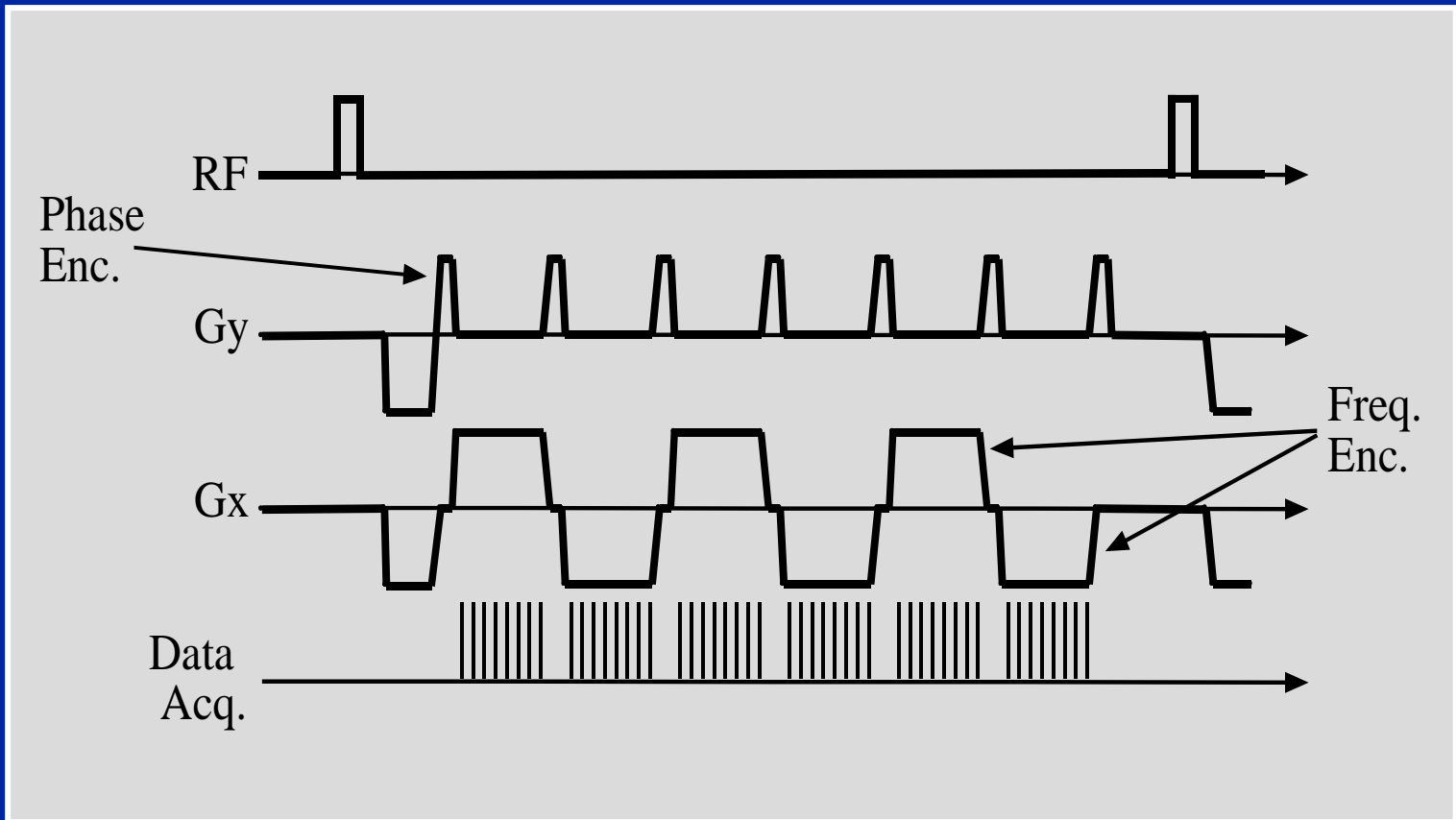


Phase Encoding
Method #1
(in y direction)

Echo-Planar Imaging

- For each RF pulse:
 - Frequency encoding is performed many times
 - All phase encoding steps are obtained
 - The entire image is acquired
- With each additional frequency encoding (each additional line in the k-space grid):
 - The phase encoding value is incremented
 - The phase encoding steps still has the appearance of “stop-action” motion

EPI Pulse Sequence



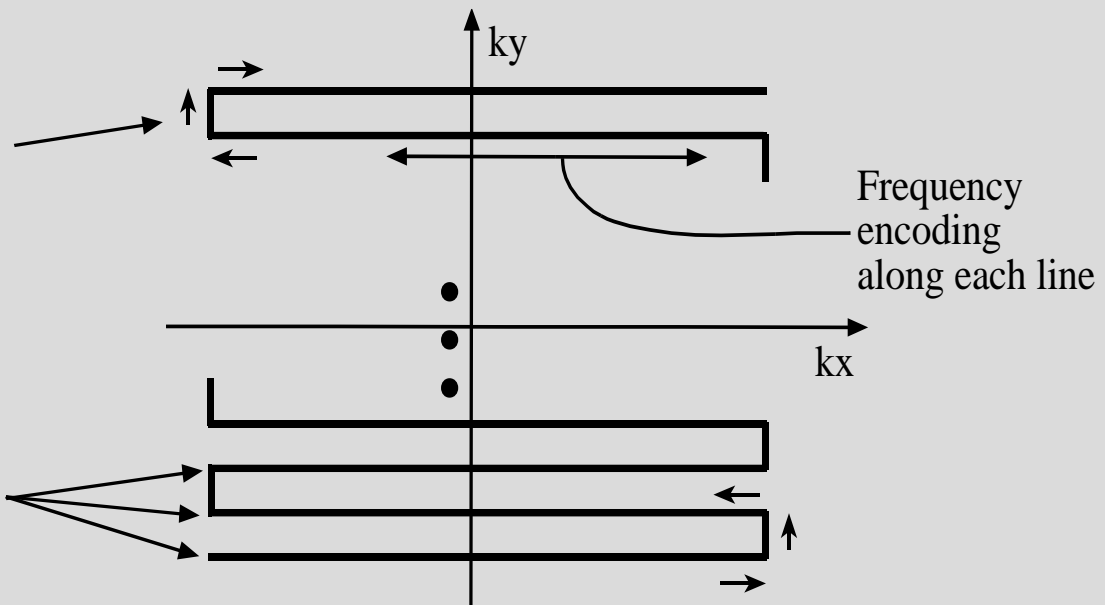
EPI Data Acquisition

- As with Spin-Warp imaging, we put the acquired data for the frequency and phase encoding into the 2D grid called “k-space.”
- Also, the 2D Fourier transform is used to create the image.
- In EPI, the data is filled into k-space in a rectangular “zig-zag”-like pattern.

EPI Data Acquisition

Changing the sign of the frequency enc. changes the direction that the data is placed into this 2D grid.

Each line has a different phase encode



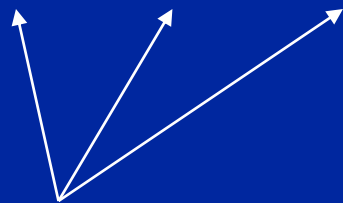
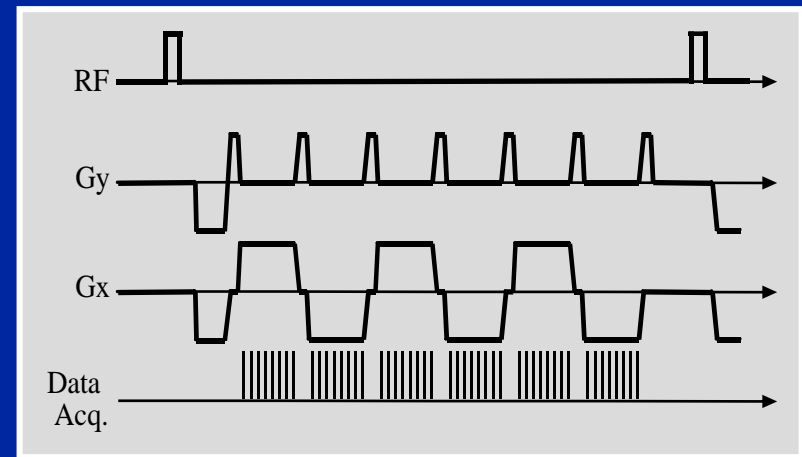
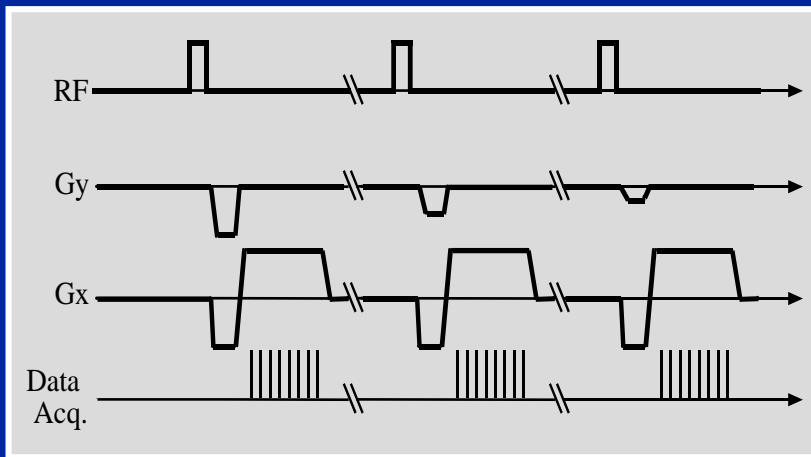
EPI Imaging

- In summary, EPI data is in many ways like Spin-Warp imaging:
 - They are combinations of two kinds of 1D localization.
 - They have both frequency and phase encoding.
 - Data are acquired on a 2D grid called k-space.
 - Images are reconstructed by a 2D Fourier transform.

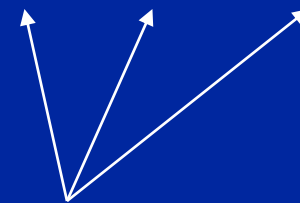
Spin-Warp vs. EPI Pulse Sequences

Spin-Warp

EPI



Many acquisitions
to make a one image.



One acquisition
to make one image.